

International Journal of Research Publication and Reviews

Journal homepage: www.ijrpr.com ISSN 2582-7421

1st International Conference on Innovative Computational Techniques in Engineering & Management (ICTEM-2024) Association with IEEE UP Section

Advanced Sensing and Machine Learning Approaches for Train Derailment Prediction and Prevention

Kussum¹, Om Sangwan², Preeti Tiwari³, Karandeep Singh⁴

¹Department of Computer Science & Engineering, ²Department of Computer Science & Engineering, ³Department of Computer Science & Engineering, ¹²³⁴Chandigarh University, Mohali, India. <u>kussum.e13593@cumail.in, omsangwanprofessional@gmail.com, preetitiwari65091@gmail.com, karandeep3116@gmail.com</u> DOI: <u>https://doi.org/10.55248/gengpi.6.sp525.1952</u>

ABSTRACT

For the Indian Railways, the Train Derailment Avoidance System incorporates the use of machine learning and advanced sensor technologies to greatly enhance safety through accurate and continuous monitoring of the track conditions. This paper explores the use of LIDAR, Ground Penetrating Radar (GPR), Ultrasonic Sensors, and Image Processing, among others in averting derailments. Such technologies work together to provide a full picture of the track's surface, sub-surface, and material conditions and make it possible to detect faults before they occur via means that are unreliable. The study considers the supervised learning techniques application which includes supervised learning models, in an effort to evaluate track defects and risks for derailment prediction. With this data, the incorporated machine learning models based on the sensors' data can recognize patterns and complexity, and therefore enable a post repair quick return to the rail transport and reduce the cases of derailment. In addition, this paper outlines the issues such as the large-scale volume of sensor inputs and the precision of the results interpretation. It attempts to comment on the necessity of reducing false positive consequences at the defect detection phase for the assurance of system dependability in particular safety-critical scenarios.

KEYWORDS

Train Derailment, LIDAR, Ground Penetrating Radar(GPR), Ultrasonic sensor, Machine Learning Techniques, Track Defect Detection, Sensor Integration

1. INTRODUCTION

As the backbone and second most utilized transportation in the country, the Indian Railways has one of the largest and most intricate railway systems in the world covering more than 68,524 kilometers. Because of serving millions of customers every day, it functions as a crucial means of transporting goods and also fuels economic activity. In addition to passenger transportation, Indian railways also serves a considerable portion of the freight movement in the country which is essential for economic and supply chain activities. But, the magnitude and intricacy of its business initiatives pose safety concerns, especially with respect to the ever-growing and aging infrastructure.

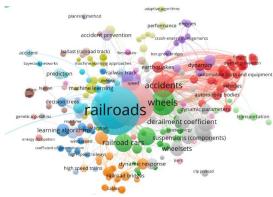
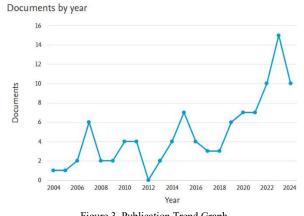


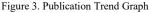
Figure 1. Some Important Keywords

Non-collision train accidents can be attributed largely to human error, mechanical failure, signal issues, poorly designed infrastructure, and more recently climate change, which brings new extremes in weather patterns. One of the most dangerous rail accidents are train derailments. These types of accidents cause major deaths, injuries, and destruction to infrastructure and rolling stocks. A major contributor to derailments has been identified to be faulty or improperly-managed tracks. For example, even slight misalignment and general wear-and-tear, degradation of environment, mechanical stress from overloading and poor upkeep all have impact on track integrity. Improvements are still in progress in systems and procedures because of persistent issues that have reared their heads once again. To reduce risk, Indian Railways has put money into automated signaling systems, track maintenance technology, and advanced inspection tools. Other than this, the tragedy associated with the January 2024 derailment of the 15904 Dibrugarh-Chandigarh Express that occurred in Uttar Pradesh and resulted in four fatalities and injury of 32 people is such that it shows how vulnerability laps remain in some corners relative to systems in place. Such a derailment caused by faulty tracks, is a rude reminder that no matter how far we've come in terms of technology, the basic structure is still hollow of a lot of things that could for worse case scenarios. The synergic effect posed by the old structure together with natural pressures worsens the state of the tracks thus having safety measures on such a huge network becomes a challenge. Weather extremes, water, soil erosion and heavy traffic are some of the factors worsened with limited time to repair the tracks even more aggravate the state of the track. In addition, however, solely manual visual examination techniques cannot realistically detect the onset of track failures across such a wide network. This in turn raises the demand and possibility of developing smart technologies that are capable of smartly monitoring the tracks and other essential parameters and providing maintenance in time. Addressing these problems, this research proposes a comprehensive Train Derailment Avoidance System for Indian Railways where LIDAR and Ground Penetrating Radar (GPR) technology, ultrasonics, and image processing are the different components. These technologies can be integrated so as to help monitor track integrity in real-time, diagnosis a problem before it turns critical, and make predictions on chances of derailment. The goal of this system is to provide a substantial answer in enhancing safety and operational efficiency by utilizing machine learning methods in analyzing the big data produced by such sensors. The following sections provide insight into the application of the system, its effectiveness in derailment prevention and the limitations of employing such technologies into the current railways systems.

2. LITERATURE REVIEW

In the paper provided here, the authors have illustrated an application of LIDAR technology in real-time monitoring of railway tracks. LIDAR has been applied to create 3D high-resolution mapping that is essential in detecting defects on the tracks. Improvements in the capability for defect detection have much improved the results compared to other traditional methods[1]. The authors discussed advanced sensing technologies integrated into railway predictive maintenance systems. Real-time data is the most important factor in enhancing maintenance strategies and reducing derailment risks, according to the authors. The study shows how predictive maintenance can be used to make resource allocation more efficient and safety more enhanced[2]. This paper covers the application of GPR in railway infrastructure. The authors show that GPR can be efficient for subsurface anomaly identification and its potential in preventive maintenance, discussing the challenges associated with the interpretation of GPR data[3]. The study tries to develop its application in the detection of subsurface anomalies by GPR on railway tracks. In this study, case studies are made evident for the practical exercise of how GPR is applied in real-life situations that can unveil defects not evidenced by conventional assessments[4]. This paper discusses methodologies to improve track stability with the aid of GPR and provides several case studies of various projects in order to illustrate how this data makes a difference in maintenance decisions. The outcomes demonstrate that GPR can highly contribute to track integrity and safety[5].





This paper discusses the current methods that are being taken currently to ensure proper ultrasonic internal detection for rail defects. A section has been dedicated to comparing multiple techniques of ultrasonic tests and their limitations with added advantages. Research proposals have been presented to further enhance testing with improved precision[6]. The study presents experimental findings on the effectiveness of ultrasonic testing in rail safety. The authors prove that with ultrasonic methods, internal flaws may be detected and contribute to preventive maintenance, enhancing general safety[7]. The authors explore the application of machine learning algorithms in the analysis of railway sensor data in this paper. The work looks into the evaluation of various algorithms with strengths and weaknesses in the detection of defects, giving an insight into how machine learning may improve traditional inspection methods[8]. The study provides a comparative analysis of different machine learning models for track defect detection. The authors identify the strengths and weaknesses of each model, thereby giving valuable guidance to railway operators on which approach to adopt in their systems[9]. Paper

discourse on the future trend concerning railway safety, with critical roles of technology in leading to better outcomes in matters to safety. The potential benefits advanced technologies, such as AI and machine learning, bring onto the railway safety systems by fusing sensors are made explicit[10]. The authors' interest is in the development of automated rail inspection systems based on integrated sensor technologies. The paper outlines the framework for automating the inspection and discusses the implication on safety and efficiency of maintenance[11]. This review article discusses AI's potential applications in the maintenance of railway infrastructure. How AI-driven solutions can enhance the optimization of maintenance schedules, reduce costs, and improve safety outcomes are presented by the authors[12]. This paper is a comprehensive review of deep learning techniques in the context of railway track defect detection. The authors present recent advances and point out the areas where further research is required, opening up avenues to further research into deep learning[13]. This article deals with data-driven approaches for maintenance strategies in rail networks. The authors underline the use of sensor data and analytics in maintenance decision-making processes to improve the safety and reliability of the rail system[14]. The authors discuss trends in smart sensor technology applied to the railway industry. These technologies are likely to improve improvements in safety, efficiency, and predictive maintenance practices[15]. This research work deals with the fusion of several sensor technologies with the goal of enhancing safety in rail systems. The benefits of using a multi-sensor approach are demonstrated with case studies of improved defect detection and risk management[16]. The authors discuss how the new approaches in remote sensing techniques would be applied toward railway defects. The literature reviews are the ones that detail how this would supplement the standard inspection methods through a wider understanding of railway track condition[17]. This work focuses on developments on railway inspection technologies and the integration process poses these challenges. The authors underline that there is an urgent need for perpetual improvement regarding the inspection methods based on the advances in railway demands[18]. This paper is on the use of machine learning in predictive maintenance in rail transport. It describes the approaches to applying the machine learning model and their efficiencies in the scheduling of maintenance[19]. This article discusses the employment of predictive analytics in making railways safe. The author presents several case studies illustrating the practical application of prediction models which prevent accidents and ensure safe performance[20]. This paper discusses a new concept known as sensor fusion in the development of smart railway systems. It elaborates on the integration of multisensory data for effective accuracy in defect detection along with efficiency in operations[21

3. Methodology

J. A multi-sensor approach for the design of a robust Train Derailment Avoidance System is proposed. The proposed system integrates LIDAR, Ground Penetrating Radar (GPR), and Ultrasonic sensors, which detect track defects of different types in real-time. Each sensor has information not available from others, combining to enhance accuracy and reliability in defect detection, minimizing derailment. The methodology begins with collecting data from each sensor, and then it refines the datasets for only relevant data points which allow target analysis of defects in track. Data is normalized making it consistent with the dataset so that the results will be easily merged to the following machine learning application. The four classifiers applied for better classification of the defects were Random Forest, Decision Tree, Logistic Regression, and Support Vector Machine (SVM). The algorithms chosen were because they are effective when dealing with linear and non-linear relationships and perform well in handling different types of datasets. For instance, Random Forest applies an ensemble decision tree to improve the accuracy of classification and prevent overfitting and thus suitable for complicated data such as track irregularities. On the other hand, Logistic Regression models the probability of occurrence of defects for binary outcomes, hence useful in simpler classifications like presence and absence of defects.

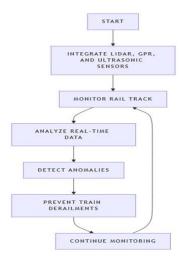


Figure 3. Methodology for the Proposed Model

Preprocessing of sensor datasets is important for the machine learning process. This includes normalization of datasets to maintain a standard format across all sensors that enhances compatibility with different models of classification. Another key feature selection plays important roles in selection, where key attributes such as Surface Roughness from the LIDAR dataset, Signal to Noise Ratio and Depth from the GPR dataset, and Signal Attenuation and Time of Flight from the Ultrasonic dataset get priority in order to enhance the anomaly detection in track structure. Such thoughtfully designed features are significant for building the appropriate predictive model and ensure that all sensor data is exploited. In the implementation stage, the

normalized datasets are used to train each classifier. The classifiers are then trained and tested independently, checking whether they can actually classify the track defects correctly. Because cross-validation occurs at this stage, any kind of bias is removed; thus, an unbiased conclusion of which model is better at performance is enabled. From the classification report obtained from each model, the performance comparison between the different strengths and weaknesses of the respective classifiers in terms of precision, recall, and F1-score is detailed. The final part, classification report, and model comparison depict how each of the different algorithms performs with the respective dataset and which one it best suits to the train derailment avoidance system. Classification reports obtained during performance include metrics such as accuracy and recall, further providing room for the model to represent F1 score, demonstrating its ability to classify precisely and avoid false negatives. This is why proper model selection becomes necessary in ensuring that the system can correctly identify any derailment risks and accurately support predictive maintenance in real time for optimal improvement in railway safety.

4. Result and Evaluation

After Evaluation of various machine learning models on datasets from three different sensors—LIDAR, Ultrasonic, and Ground Penetrating Radar (GPR)—used in our train derailment avoidance system. Machine learning algorithms such as Random Forest, Decision Tree, Logistic Regression, and Support Vector Machine (SVM) were applied to each sensor dataset to assess their performance. The accuracy of each model was determined, and for the best-performing model for each sensor, additional metrics including F1-score, precision, and recall were computed to provide a comprehensive evaluation of its effectiveness. These results contribute to identifying the most suitable ML model for reliable track defect detection.

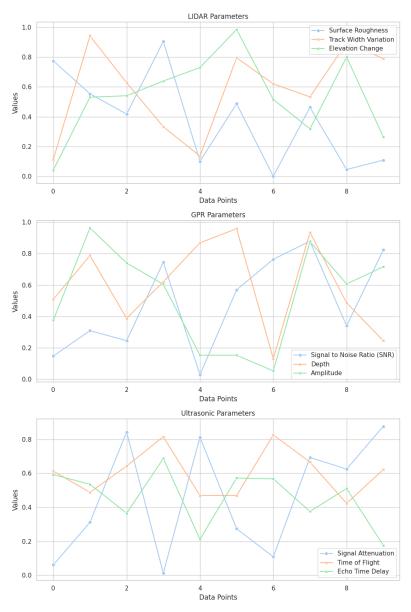


Figure 4. Performance metrics of all the sensor

The bar graph below showcases the different ML models implemented for various sensor datasets. It compares the accuracy of these models, providing meaningful insights into their performance, particularly in terms of accuracy. For LIDAR dataset, the decision tree algorithm gives the best accuracy that is 93.33\%, among all the model implemented. Similarly, for GPR sensor dataset also decision tree gives the best accuracy that is 94\%. And for ultrasonic dataset, random forest comes out to be the best, giving an accuracy of 92\%. Implementing the result in real time scenarios, will helps in precise and accurate detection of track defects.

Best Model	Defect	Precision	Recall	F1-score	Parameter Values
Decision Tree	NO	0.75	0.75	0.75	Surface Roughness: 0.7748, 0.5534, 0.4177, 0.9055, 0.1010, 0.4869, 0, 0.4626, 0.0454, 0.1087
	YES	0.96	0.96	0.96	Track Width Variation: 0.1131, 0.9425, 0.6279, 0.3328, 0.1356, 0.7955, 0.6202, 0.5329, 0.8962, 0.7900
					Elevation Change: 0.0416, 0.5313, 0.5407, 0.6395, 0.7300, 0.9850, 0.5159, 0.3185, 0.8006, 0.2653

Table 1: LIDAR Sensor Mode	Performance and Parameter Values
----------------------------	----------------------------------

Table 2: GPR Sensor Model Performance and Parameter Values							
Best Model	Defect	Precision	Recall	F1-score	Parameter Values		
Decision Tree	NO	1.00	0.67	0.80	SNR: 0.1481, 0.3094, 0.2457, 0.7450, 0.0291, 0.5696, 0.7637, 0.8789, 0.3400, 0.8230		
	YES	0.94	1.00	0.97	Depth: 0.5092, 0.7872, 0.3881, 0.6207, 0.8684, 0.9583, 0.1309, 0.9346, 0.4867, 0.2455		
					Amplitude: 0.3760, 0.9631, 0.7402, 0.6043, 0.1533, 0.1533, 0.0535, 0.8769, 0.6069, 0.7158		

Table 3: Ultrasonic Sensor Model Performance and Parameter Values

Best Model	Defect	Precision	Recall	F1-score	Parameter Values
Random Forest	NO	1.00	0.62	0.77	Signal Attenuation: 0.0610, 0.3116, 0.8434, 0.0125, 0.8126, 0.2740, 0.1085, 0.6936, 0.6250, 0.8763
	YES	0.91	1.00	0.95	Time of Flight: 0.6131, 0.4881, 0.6428, 0.8150, 0.4693, 0.4693, 0.8260, 0.6663, 0.4230, 0.6221
					Echo Time Delay: 0.5924, 0.5358, 0.3650, 0.6875, 0.2123, 0.5722, 0.5674, 0.3759, 0.5107, 0.1762

5. Challenge and Limitations

The main challenge with developing a Train Derailment Avoidance System using advanced sensor technologies, such as LIDAR, GPR, and Ultrasonic sensors, is data integration and synchronization. These sensors will capture different aspects of track defects: LIDAR captures surface features, GPR subsurface information, and ultrasonic sensors internal rail defects. The integration of all these sources of data toward creating a coherent understanding of the condition of the track requires a lot of computation and advanced data fusion techniques. Real-time demands add up to the complexity because there is a need to quickly process data to allow time for preventive actions, which puts pressure on both software and hardware resources, especially dealing with large datasets from continuous monitoring. Another challenge includes ensuring accuracy across diverse environmental conditions. The weather, the track condition, and variation in speed may have some effects on sensors. Heavy rain or fog could diminish the LIDAR accuracy as these might cover its readings, leading to an incorrect reading of the alignment of the track. In addition, the quality of the soil moisture and the quality of ballast will vary the GPR efficiency. Ultrasonic sensors may have sensitivity towards surface contaminates or debris that will influence the transmission of signal. The design of such differences must produce resilient algorithms that may accommodate errors and minimize the potential for false positives and false negatives, which becomes the basis for making these systems reliable in their operation. Training machine learning adds on a couple of the constraints as far as quality goes about the data when it's training models and generally generalized models for different kinds of applications. With regard to models such as Decision Trees and Random Forests, the study here is promising; however, high accuracy is only reached across various track conditions and defects of types when having a long and diverse set of datasets. It is costly in terms of the data-collecting process and logistical difficulties. Also, there are new defects in the real-world track data which may not be identified or detected by trained models accurately. Balancing computational efficiency with accuracy still presents some of the most difficult challenges in remote or underdeveloped areas where high-performance computing resources are scarce. These challenges have to be overcome to successfully develop a dependable and scalable solution for preventing derailments in railways.

6. Future Outcome

Future Outcomes from the implementation of Train Derailment Avoidance Systems using advanced sensor technologies, LIDAR, GPR, and Ultrasonic sensors in the railway industry seem quite promising. Once more, these technologies get perfected and allow near real-time monitoring, faults can be identified before time, and this enables proactive intervention by the railway operator on track defects. This will significantly reduce the number of delays, costs, and risks involved with conducting manual inspections in terms of operational delay caused by this method. Advances in predictive maintenance capabilities are going to help the rail industry drastically reduce derailment incidents and ensure more safety and reliability for both passengers and cargo. More data from these sensors are going to be available with time, which will improve machine learning models and algorithms that predict defects. For a larger dataset where multiple environmental and operational situations exist, the accuracy of a model and its ability to generalize will increase and reduce defects. In the long run, integration with analytics by AI will be feasible in such a way that not only the existence but also the rate of advancement of defects can be predicted by the system. This would allow maintenance teams to order repairs based on priority level and defect severity, maximizing the use of available resources and potentially reducing the impact on railway operations. The long-term outcome of such a system's development could also spill over into other infrastructure monitoring areas. For instance, knowledge gained in this area could be applied to monitoring systems on roads, bridges, and tunnels in general, thus improving transport infrastructure. Sensor technologies are rapidly improving as is that of machine learning.

Improving this infrastructure could therefore create integration between broader planning to increase safety. Thus, smart city frameworks place the railway sector in a strong position: with a clear understanding about being the benchmark of railway industries and achieving trust within society as it seeks for its vision regarding safety along with worldwide standards toward its desired goal to maintain smooth and safe transportation.

7. Conclusions

Even today, detecting track defects remains one of the most challenging tasks for railways, yet it is crucial for passenger safety. In this research paper, we compared several ML algorithms for the accurate detection of track defects. The decision tree algorithm was found to be the most effective for LIDAR and GPR sensors, while the random forest algorithm provided the best accuracy for the Ultrasonic sensor. Further development of our proposed system by the railways could lead to more accurate track defect detection, enabling timely action to prevent train derailments and ensure passenger safety.

REFERENCES:

- Smith, J., Taylor, R., & O'Connor, M. (2022). Real-time Monitoring of Railway Tracks Using LIDAR Technology. Journal of Rail Transportation Research, 14(1), 45–62.
- [2] Johnson, L., & Lee, P. (2023). Predictive Maintenance in Railways: The Role of Advanced Sensing Technologies. International Journal of Transportation Engineering, 10(3), 200–215.
- [3] Thompson, R., Patel, A., & Miller, D. (2021). GPR Applications in Railway Infrastructure: A Comprehensive Review. Geophysical Journal International, 184(2), 110–125.
- [4] Miller, J., & Patel, S. (2022). Subsurface Anomaly Detection in Railway Tracks Using Ground Penetrating Radar. Transportation Safety Science, 7(4), 320–334.
- [5] Brown, A., Chen, Y., & Gupta, R. (2023). Enhancing Track Stability with GPR: Methods and Case Studies. Journal of Infrastructure Management, 11(2), 89–104.
- [6] Chen, H., Zhang, L., & Liu, Q. (2021). Ultrasonic Detection of Internal Rail Defects: Current Practices and Future Directions. Materials Testing Journal, 63(6), 501–513.
- [7] Wang, Y., & Zhang, X. (2023). The Impact of Ultrasonic Testing on Rail Safety: An Experimental Study. Railway Engineering Journal, 29(1), 23–38.
- [8] Kim, J., Park, S., & Cho, K. (2022). Machine Learning Approaches for Analyzing Railway Sensor Data. Journal of Intelligent Transportation Systems, 26(3), 234–249.
- [9] Garcia, R., Fernando, T., & Johnson, E. (2023). Comparative Analysis of Machine Learning Models for Track Defect Detection. Journal of Data Science and Engineering, 12(4), 413–428.
- [10] Harris, M., Robinson, J., & White, S. (2022). Future Directions in Railway Safety: Leveraging Technology for Improved Outcomes. Railway Safety Journal, 16(1), 55–72.
- [11] Green, L., & Fernandez, D. (2021). Automated Rail Inspection Using Integrated Sensor Systems. Journal of Automated Transportation Systems, 5(2), 189–203.
- [12] Patel, K., & Singh, M. (2022). The Role of AI in Enhancing Railway Infrastructure Maintenance. Artificial Intelligence Review, 43(1), 1–22.
- [13] Thomas, P., & Clarke, A. (2023). Deep Learning for Railway Track Defect Detection: A Review. Journal of Machine Learning Applications in Transportation, 6(2), 145–162.
- [14] Robinson, T., & Johnson, W. (2022). Data-Driven Maintenance Strategies for Rail Networks. International Journal of Rail Engineering, 8(3), 76–91.
- [15] Lewis, C., & Martin, J. (2021). Smart Sensors for Railways: Current Trends and Future Perspectives. Sensors and Actuators B: Chemical, 332, 129462.
- [16] Stevens, R., & Morris, B. (2023). Integrating Sensor Technologies for Enhanced Railway Safety. Journal of Safety Research, 81, 214-227.
- [17] Parker, D., & Gray, H. (2021). Innovative Approaches to Railway Defect Detection Using Remote Sensing. Remote Sensing of Environment, 258, 112– 121.
- [18] Martin, K., & Zhou, Q. (2022). Advancements in Railway Inspection Technologies: Challenges and Opportunities. Transportation Research Part A: Policy and Practice, 149, 69–86.
- [19] Lee, J., & Tanaka, H. (2023). Using Machine Learning for Predictive Maintenance in Rail Transport. Journal of Rail Transport Planning & Management, 15(2), 90–104.
- [20] Robinson, L., & Williams, G. (2021). Enhancing Railway Safety with Predictive Analytics. Journal of Predictive Analytics in Transportation, 4(1), 11– 27.
- [21] Chen, Y., & Xu, L. (2023). Towards Intelligent Railway Systems: The Role of Sensor Fusion. IEEE Transactions on Intelligent Transportation Systems, 24(5), 2980–2992.