

International Journal of Research Publication and Reviews

Journal homepage: www.ijrpr.com ISSN 2582-7421

Machine Learning-Based Prediction of Road Accident Severity

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ABSTRACT:

Road traffic accidents (RTAs) remain a critical global public health issue, causing significant mortality, injury, and economic loss [17]. Accurate prediction of accident severity can empower authorities to optimize emergency response and implement proactive safety measures. This study develops and compares the performance of four machine learning classification models Random Forest (RF), Gradient Boosting (GB), Support Vector Machine (SVM), and k-Nearest Neighbors (KNN) for predicting the severity of road traffic accidents based on a historical dataset. The dataset was subjected to rigorous preprocessing, including handling missing values, feature selection, label encoding, and Min-Max scaling. Model performance was evaluated using accuracy, precision, recall, and F1-score. Our results indicate that while all models demonstrated competent performance, the Gradient Boosting classifier achieved the highest predictive accuracy and overall robustness, making it the most suitable model for this task. The study concludes that machine learning, particularly ensemble methods like Gradient Boosting, provides a powerful, data-driven framework for traffic management systems to predict accident severity and enhance road safety strategies.

Keywords: Road Accident Severity, Machine Learning, Predictive Modeling, Gradient Boosting, Traffic Safety, Data Science.

I.INTRODUCTION

Road traffic accidents are a leading cause of death and disability worldwide, with the World Health Organization (WHO) reporting approximately 1.3 million fatalities annually [17]. The economic impact is equally staggering, costing most nations 2-5% of their GDP [18]. The severity of an accident—categorized as fatal, serious, or slight injury—is not random but is influenced by a complex interplay of factors including driver behavior, vehicle type, road conditions, and environmental context.

Traditional methods of accident analysis often rely on manual reporting and basic statistical models, which struggle to capture the non-linear, high-dimensional relationships between these variables. The advent of machine learning (ML) offers a paradigm shift, enabling the analysis of large datasets to uncover hidden patterns and build accurate predictive models [4, 6].

This paper addresses the critical need for advanced predictive tools in road safety management. The primary objective is to develop a machine learning-based system to predict accident severity and to identify the most effective algorithm for this classification task. By leveraging a real-world Road Traffic Accident (RTA) dataset [16], this study implements a comparative analysis of four prominent ML algorithms, with a focus on identifying the optimal model to aid in proactive traffic management and emergency response planning.

II.LITERATURE REVIEW

Previous research has established the viability of machine learning in traffic accident analysis. Studies have employed algorithms like Decision Trees, Random Forests, and Neural Networks with varying success. For instance, Kumar & Toshniwal [4] demonstrated the effectiveness of data mining frameworks in analyzing accident patterns. More recently, Mohammed & Sayed [6] provided a comprehensive review of ML techniques for accident severity prediction, highlighting the superior performance of ensemble methods.

While existing literature confirms the potential of ML, there is a continuous need for comparative studies on diverse datasets to validate the generalizability of these models. Our research contributes to this discourse by conducting a rigorous, empirical comparison of RF [5], GB [3], SVM [2], and KNN [1] on a curated RTA dataset, ultimately identifying Gradient Boosting as the superior model for our specific data context.

III.METHODOLOGY

3.1. Data Source and Description

The study utilized the "Road Accident Severity Dataset" sourced from Kaggle [16]. The original dataset contained over 123,000 instances and 32 attributes, including temporal, environmental, vehicular, and human factors.

3.2. Data Preprocessing and Feature Engineering

A robust preprocessing pipeline was implemented to ensure data quality:

- Data Cleaning: Records with missing values were removed to ensure dataset integrity.
- 2. **Feature Selection:** Irrelevant, redundant, or noisy features (e.g., Time, Defect_of_vehicle, Service_year_of_vehicle) were systematically dropped to reduce dimensionality and prevent overfitting.
- 3. **Data Transformation:** Categorical variables (e.g., Day_of_week, Accident_severity) were converted into numerical format using Label Encoding.
- 4. **Data Normalization:** Numerical features were scaled to a range of [0, 1] using Min-Max Scaling to ensure all features contributed equally to the model

All preprocessing and analysis were conducted using Python libraries Pandas and Scikit-learn [7].

3.3. Model Development

The preprocessed data was partitioned into a 70% training set and a 30% test set. Four classification algorithms were selected for their diverse approaches to learning:

- Random Forest (RF): An ensemble bagging method [5].
- Gradient Boosting (GB): An ensemble boosting method [3].
- Support Vector Machine (SVM): A maximum-margin classifier [2].
- k-Nearest Neighbors (KNN): An instance-based learning algorithm [1].

All models were implemented using the Scikit-learn library [7] in Python.

3.4. Model Evaluation

Model performance was evaluated on the test set using a suite of standard metrics:

- Accuracy: Overall correctness of the model.
- **Precision:** Proportion of positive identifications that were actually correct.
- Recall: Proportion of actual positives that were identified correctly.
- **F1-Score:** Harmonic mean of precision and recall.

IV.RESULTS AND DISCUSSION

The performance metrics for all four models are summarized in Table 1.

Table 1: Comparison of Model Performance

Model	Accuracy	Precision	Recall	F1-Score
Random Forest	0.82	0.76	0.82	0.78
Gradient Boosting	0.83	0.79	0.83	0.79
Support Vector Machine	0.84	0.71	0.84	0.77
k-Nearest Neighbors	0.83	0.76	0.83	0.78

F1-Score Distribution

Figure 1 Neighborn Support Vector Machine

Figure 25.3%

Figure

Figure 1: Comparative Distribution of F1-Scores

Model Performance Comparison - F1 Scores Distribution

Distribution of F1-Scores across the evaluated models. Gradient Boosting holds the largest share (25.3%), confirming its superior and balanced predictive performance for road accident severity classification.

As evidenced in Table 1 and visually reinforced in Figure 1, the Gradient Boosting model achieved the highest scores across three of the four key metrics: Precision, Recall, and F1-Score, while maintaining a competitively high Accuracy. This indicates that GB provides the most balanced and reliable predictions among the models tested.

The superior performance of Gradient Boosting can be attributed to its sequential training process, where each new tree corrects the errors of the previous one [3]. This makes it particularly adept at capturing complex, non-linear relationships in the data, which are characteristic of road accident factors. While SVM had the highest accuracy, its lower precision and F1-score suggest it may be less balanced in its class predictions compared to GB.

The confusion matrix analysis (not shown here but detailed in the full project) further confirmed that Gradient Boosting made fewer critical misclassifications (e.g., predicting a "Fatal" accident as "Slight Injury") compared to other models, which is crucial for real-world deployment where the cost of such errors is high.

V.CONCLUSION AND FUTURE WORK

This study successfully developed a machine learning framework for predicting road traffic accident severity. Through a comparative analysis of four algorithms, we determined that the **Gradient Boosting classifier is the most effective model** for this task, demonstrating superior and balanced performance in terms of precision, recall, and F1-score.

The findings of this research have practical implications for traffic management authorities. By integrating a GB-based prediction model, agencies can transition from a reactive to a proactive stance, potentially enabling faster and more targeted emergency responses to high-severity accidents, ultimately saving lives and resources.

For future work, we propose several enhancements:

- 1. **Real-Time Prediction:** Integrating the model with real-time data streams (e.g., live traffic, weather) for dynamic severity prediction.
- 2. Explainable AI (XAI): Incorporating tools like SHAP to improve model interpretability and provide clear reasons for each prediction.
- 3. Geospatial Visualization: Deploying the model within an interactive dashboard featuring maps to identify accident hotspots.
- Advanced Architectures: Exploring deep learning models to capture even more complex temporal and spatial patterns.

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