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Iot- Paralysis Patient Health Care System

Syed Atif Ali¹, M.A Anzer Moith², Mohammed Shoaib Ali³, Mrs.Amena Begum ⁴

UG students, Assistant Professor, Electronic and Communication Engineering, Deccan College of Engineering And Engineering, Hyderabad, Telangana

ABSTRACT:

Many people in the modern world have physical limitations brought on by accidents or paralysis. The majority of these patients are reliant on their careers. A condition known as paralysis occurs when one or more bodily muscles are impaired. Play some music to help these patients' hands large part in the system. The mechanism makes sure that the patient can gesture his needs. Sometimes a patient's hand motions can also operate equipment. This system also keeps an eye on the patient's heart rate; if it rises above the normal range, a buzzer will sound and an LCD message advising doctors and careers to respond to the patient will appear.

Introduction:

Paralysis is the inability to move muscles on your own and with purpose. It can be temporary or permanent. The most common causes are stroke, spinal cord injury, and multiple sclerosis. Paralysis can be a complete loss of movement known as plegia, or a significant weakness called paresis. Paralysis is most often caused by damage in the nervous system, especially the spinal cord. Other major causes are stroke, trauma with nerve injury, poliomyelitis, cerebral palsy, peripheral neuropathy, Parkinson's disease, ALS, botulism, spina bifida, multiple sclerosis, and Guillain–Barré syndrome. For example, monoplegia/monoparesis is complete loss of movement or weakness of one limb. Hemiplegia/hemiparesis is complete loss of movement or weakness of arm and leg on same side of the body. Paraplegia/paraparesis is complete loss or weakening of both legs. Tetraplegia/tetraparesisor quadraplegia/quadraparesis is complete loss or weakness of both arms and both legs. Paralysis is caused by injury or disease affecting the central nervous system (brain and spinal cord) which means that the nerve signals sent to the muscles is interrupted. Paralysis can also cause a number of associated secondary conditions, such as urinary incontinence and bowel incontinence. Even though, there are innovative approaches for curing or treating paralysis patients, but the aim of treatment is to help a person adapt to life with paralysis by making them as independent as possible. Where we see a problem with these types of devices that are being developed is that they are very large and expensive machines. They seem to be only available in hospitals and not able to be used at the patients home or at their convenience. Our goal is to make a device that will be able to retrain a patient's motion but have them be able to use.

What is aim of Iot paralysis patient health care system?

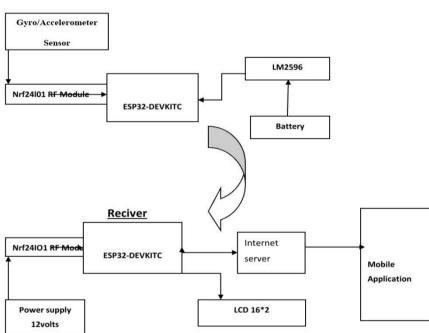
The aim of the innovation landscape of healthcare, an IoT-enabled system for paralysis patients revolutionizes care delivery. By integrating sensors and devices into a unified network, real-time data on vital signs, movement patterns, and environmental conditions are gathered, offering comprehensive insights into the patient's health status. Machine learning algorithms analyze this data to predict potential health complications, enabling proactive interventions. Wearable devices equipped with actuators provide personalized rehabilitation routines, enhancing mobility and functionality. Telemedicine platforms facilitate remote consultations, ensuring continuous monitoring and immediate medical attention. Cloud-based storage securely maintains patient records and facilitates seamless information sharing among healthcare providers, optimizing collaboration and decision-making. This interconnected ecosystem not only empowers patients with greater autonomy but also enhances the efficiency and effectiveness of paralysis healthcare management, ultimately improving the quality of life for individuals living with paralysis.

Why is Iot paralysis patient health care system?

The necessity behind this project stems from The IoT-based healthcare system for paralysis patients is crucial for several reasons. Firstly, it provides continuous monitoring of vital signs, movements, and environmental conditions, allowing for early detection of complications. Secondly, personalized rehabilitation programs delivered through wearable devices promote mobility and independence. Thirdly, telemedicine facilitates remote consultations, ensuring timely access to healthcare professionals. Additionally, predictive analytics identify potential health risks, enabling proactive interventions to prevent adverse events. Furthermore, centralized data storage facilitates seamless information sharing among healthcare providers, enhancing collaboration and decision-making. Overall, this system empowers patients to actively engage in their care while optimizing healthcare delivery, ultimately improving the quality of life for individuals living with paralysis.

METHODOLOGY

The development of the IoT-based healthcare communication system for paralysis patients involves several key stages, focusing on hardware setup, software development, wireless communication, data processing, and integration with cloud services.Firstly, on the transmitter side, the hardware setup includes an ESP32, MPU6050 (gyroscope and accelerometer), and NRF24L01 module. The MPU6050 sensor is connected to the ESP32 using the I2C protocol, with SDA to GPIO 21 and SCL to GPIO 22. The NRF24L01 module is connected to the ESP32 using the SPI protocol, with CE to GPIO 9, CSN to GPIO 10, SCK to GPIO 18, MOSI to GPIO 23, and MISO to GPIO 19. Ensuring proper power supply, typically 3.3V, is crucial for the components.On the receiver side, the hardware setup involves another ESP32, an NRF24L01 module, and a 16x2 LCD with an I2C module. The NRF24L01 is connected similarly to the transmitter side. The 16x2 LCD is connected to the ESP32 using the I2C protocol, with SDA to GPIO 21 and SCL to GPIO 22. Proper power supply is again necessary for reliable operation. The software development for the transmitter side includes initializing the MPU6050 sensor and the NRF24L01 module. The ESP32 continuously reads movement data from the MPU6050 sensor and interprets specific movements into predefined commands, such as tilting up for "Need water."



<u>Transmitter</u>

FIG NO 1: BLOCK DIAGRAM OF IOT PARALYSIS PATIENT HEALTH CARE SYSTEM

These commands are then transmitted wirelessly using the NRF24L01 module. On the receiver side, the software development involves initializing the NRF24L01 module, the 16x2 LCD, and setting up Wi-Fi for Firebase connectivity. The ESP32 on the receiver side continuously listens for incoming commands from the transmitter side. Upon receiving a command, it displays the information on the 16x2 LCD and updates the Firebase database with the received command. This ensures that the data is accessible remotely, allowing caregivers to monitor and respond to the patient's needs in real time. Integrating Firebase involves setting up a Firebase project and database, configuring the ESP32 to connect to Firebase, and ensuring that received commands are correctly updated in the database. A mobile application connected to the Firebase database provides real-time notifications to caregivers or family members, ensuring they are promptly informed of the patient's needs. Overall, this methodology ensures the development of a reliable, efficient, and user-friendly communication system that significantly improves the quality of life for paralysis patients, enabling them to communicate their needs effectively and reducing the caregiving burden.

How does Paralysis Patient Health Care System works

The IoT-based healthcare communication system for paralysis patients functions through an integration of hardware and software components, enabling effective communication of patient needs to caregivers. The system begins with the patient wearing a device equipped with an MPU6050 gyroscope and accelerometer sensor connected to an ESP32 microcontroller. This sensor continuously monitors the patient's movements, such as tilting the head up or down, which are predefined to correspond to specific commands, like indicating a need for water.

The ESP32 processes the raw data from the MPU6050 sensor, running algorithms that analyze the movement data to identify matches with predefined patterns. When a match is detected, the corresponding command is generated. This command is then sent to an NRF24L01 module, which transmits it wirelessly to the receiver side.

On the receiver side, another ESP32 connected to an NRF24L01 module receives the transmitted commands. The ESP32 on the receiver side continuously listens for incoming data from the transmitter. Once a command is received, it processes the data and sends the information to a 16x2 LCD with an I2C interface, displaying the command for immediate caregiver attention. Simultaneously, the ESP32 on the receiver side updates a Firebase database with

the received command, facilitated by its internet connection via Wi-Fi. This ensures that the command is logged and can be accessed remotely. A mobile application linked to the Firebase database receives real-time updates, sending notifications to caregivers or family members to inform them of the patient's needs, even when they are not near the display.

The user interaction with the system is straightforward, as the patient only needs to perform simple, predefined movements. Caregivers monitor the 16x2 LCD display for immediate needs and receive mobile notifications for remote awareness. This integrated approach ensures that the patient's needs are communicated effectively and promptly, improving their quality of life and reducing the caregiving burden.

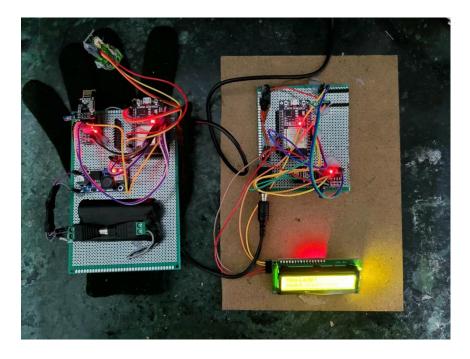


FIG NO 2: CIRCUIT DIAGRAM

Hardware Requirements:

- 1. ESP32: It provide and Bluetooth connectivity to Embedded Device.
- 2. nRF24L01: A radio transreciver module which helps to send and recive data at ism operating frequency.
- 3. 16*2 Lcd Module: it is used to see the out out.
- 4. I2C Module: used for communication protocol for characters graphic and segment lcd .
- 5. Battery: A rechargeable battery used to power the circuit.
- 6. Gyroscope: it is used to detect the change in rotation angle per unit of time

OBJECTIVES

This IoT system tackles key challenges faced by paralysis patients: limited independence, communication difficulties, and health risks. It aims to:

- Boost Patient Independence Control their environment and communicate needs
- Enhance Care Coordination: Facilitate communication and data sharing between patients, caregivers, and healthcare professionals

RESULT

The implementation of the IoT-based healthcare communication system for paralysis patients yielded promising results, showcasing significant advancements in patient-caregiver communication and enhancing the quality of life for patients.

The system successfully detected specific movements using the MPU6050 gyroscope and accelerometer sensor, enabling patients to communicate their needs through simple gestures. The sensitivity and accuracy of the sensor ensured reliable detection of predefined movements, such as tilting the head up or down, which were translated into actionable commands.

Through stable wireless communication facilitated by NRF24L01 modules, commands generated by the transmitter ESP32 were efficiently transmitted and received by the receiver ESP32 without delays or data loss. This ensured that caregivers received real-time updates on the patient's needs.



FIG NO:3 OUTPUT OF THE PROJECT

The integration of a 16x2 LCD with I2C interface on the receiver side provided a clear and immediate display of the received commands. Caregivers could easily view the patient's needs on the LCD screen, allowing for prompt responses and improved caregiving efficiency. Furthermore, the system seamlessly integrated with Firebase, allowing for the real-time updating of commands to a cloud database. This enabled remote access to patient needs, with caregivers receiving instant notifications through a mobile application connected to the Firebase database.

FUTURE SCOPE:

The future scope for IoT paralysis patient healthcare systems is expansive. Firstly, advancements in sensor technology will enable even more precise monitoring of vital signs and movements. Secondly, machine learning algorithms will become more sophisticated, allowing for better prediction of health complications and personalized treatment plans. Thirdly, wearable devices will continue to evolve, offering enhanced rehabilitation capabilities and greater comfort for patients. Additionally, telemedicine platforms will become more integrated and user-friendly, facilitating seamless remote consultations. Furthermore, the integration of virtual reality and augmented reality technologies may revolutionize rehabilitation therapies. Overall, the future holds immense potential for IoT-driven healthcare systems to further improve the quality of care and outcomes for paralysis patients..

CONCLUSION:

This This system In conclusion living with paralysis. In conclusion, the IoT-enabled healthcare system for paralysis patients represents a groundbreaking paradigm shift in care delivery. By harnessing the power of interconnected devices, sensors, and advanced analytics, this system offers a comprehensive approach to monitoring, rehabilitation, and treatment. Through real-time data collection and analysis, it enables early detection of health complications and proactive interventions, ultimately improving patient outcomes. Wearable devices equipped with actuators provide personalized rehabilitation programs, enhancing mobility and independence. Telemedicine platforms facilitate remote consultations, ensuring continuous access to healthcare professionals and support. Moreover, the seamless sharing of information among healthcare providers fosters collaboration and informed decision-making. As technology continues to evolve, the future of IoT paralysis patient healthcare systems holds promise for even greater advancements in precision, efficiency, and patient-centered care, ultimately enhancing the quality of life for individuals living with paralysis.

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