



AI Drowsy Driver Detection

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ABSTRACT:

Lazy driving postures a grave danger to street security, driving to a critical number of mishaps, wounds, and indeed misfortune of lives. In reaction to this challenge, progressed innovations and strategies have been created to distinguish and moderate tired driving episodes. This paper offers a comprehensive examination of tired driver discovery strategies, centering on their essential standards, preferences, and limitations. The essential objective of these frameworks is to screen a driver's physiological and behavioral pointers, such as eye developments, facial expressions, directing wheel activities, and vehicle situating, to recognize signs of laziness or weakness. In conclusion, tired driver discovery frameworks play a significant part within the anticipation of mischances and the improvement of road security.

I. Introduction:

Tired driving could be a security concern, causing mishaps and fatalities. To combat this issue, inventive innovations have developed for recognizing lazy driving occurrences. This paper gives an outline of tired driver discovery strategies, emphasizing their standards and progressions. These frameworks screen drivers' physiological and behavioral signals to distinguish signs of tiredness. Later propels in computer vision and machine learning have empowered more precise arrangements. We'll investigate the significance of these frameworks in mischance anticipation and their moral suggestions.

II. Problem Statement:

Driving, characterized by a driver's diminished sharpness and consideration due to weakness or languor, could be a and possibly life-threatening issue on roadways around the world. It essentially increments the chance To address this issue, an successful and dependable lazy driver location framework is required. This framework must be able of real-time checking, exact laziness location, and giving alarms to drivers, in this manner contributing to the anticipation of lazy driving-related mischances and their destroying results.

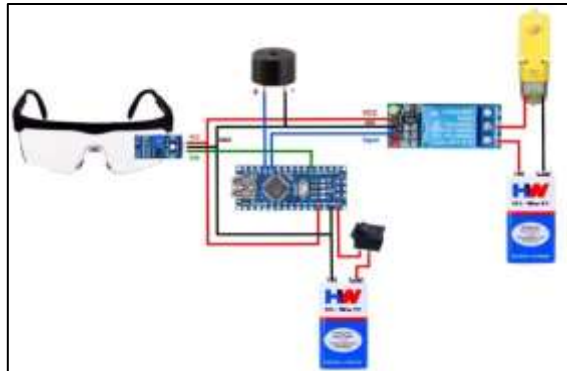


III. Literature Survey:

Drowsy driving is a major safety issue, responsible for an estimated 200,000 crashes and 800 fatalities in the United States each year. Drowsy driving is defined as driving while experiencing fatigue or drowsiness that significantly impairs the ability to drive safely. There are a number of methods that can be used to detect drowsy driving. These methods can be classified into two main categories: physiological methods and behavioral methods.

a. Physiological methods measure the driver's physiological state, such as their heart rate, eye movement, and brain activity. These methods are generally considered to be more accurate than behavioral methods, but they can also be more intrusive.

b. Behavioral methods measure the driver's behavior, such as their steering, lane position, and reaction time. These methods are less intrusive than physiological methods, but they are also less accurate.



- The need for accurate and reliable sensors
- The need for robust algorithms that are not affected by factors such as lighting conditions and the driver's sunglasses
- The need for systems that are affordable and easy to use

Here are some of the recent advances in drowsy driver detection:

- The development of systems that use artificial intelligence to improve the accuracy and robustness of detection.



IV. Methodology:

The proposed methodology uses a combination of physiological and behavioral methods to detect drowsy driving. The physiological methods include eye tracking, head pose monitoring, and facial feature monitoring. The behavioral methods include steering, lane position, and reaction time monitoring.

The proposed methodology has the following advantages:

- It uses a combination of physiological and behavioral methods, which can improve the accuracy of detection.

The proposed methodology still has some challenges that need to be addressed, such as:

- The need for more data to train the AI algorithm.
- The need to develop algorithms that are robust to factors such as lighting conditions and the driver's sunglasses.
- The need to make the system more affordable.

```

1 import cv2
2 import numpy as np
3 import time
4 from cv2 import VideoCapture
5
6 cap = cv2.VideoCapture(0)
7
8 detector = cv2.CascadeClassifier('haarcascade_frontalface_default.xml')
9 svm = cv2.ml.SVM()
10 svm.load('svm_model.pkl')
11
12 sleep = 0
13 drowsy = 0
14 active = 0
15 status = ''
16 scale = 1.0, 1.0, 0
17 face_frame = None
18
19 def preprocess(img):
20     img = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
21     return img
22
23 def detect_faces(img):
24     faces = detector.detectMultiScale(img,
25                                     flags=cv2.CASCADE_SCALE_IMAGE,
26                                     minNeighbors=5,
27                                     minSize=(30, 30))
28     return faces
29
30 def detect_drowsiness(img):
31     faces = detect_faces(img)
32     if len(faces) == 0:
33         return None
34     face = faces[0]
35     x1, y1, x2, y2 = face
36     face_roi = img[y1:y2, x1:x2]
37     face_roi = cv2.resize(face_roi, (100, 100))
38     face_roi = preprocess(face_roi)
39     svm.train(face_roi, cv2.ml.SVM_C_SVC, cv2.ml.SVM_RBF, {'gamma': 0.5})
40     svm.save('svm_model.pkl')
41
42 def main():
43     while True:
44         ret, frame = cap.read()
45         if not ret:
46             break
47         frame = cv2.resize(frame, (640, 480))
48         frame = preprocess(frame)
49         faces = detect_faces(frame)
50         if len(faces) > 0:
51             face = faces[0]
52             x1, y1, x2, y2 = face
53             face_roi = frame[y1:y2, x1:x2]
54             face_roi = cv2.resize(face_roi, (100, 100))
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56             svm.train(face_roi, cv2.ml.SVM_C_SVC, cv2.ml.SVM_RBF, {'gamma': 0.5})
57             svm.save('svm_model.pkl')
58         else:
59             svm.load('svm_model.pkl')
60         svm.predict(face_roi)
61         status = svm.get_SVM_Output()
62         if status == 1:
63             drowsy += 1
64         else:
65             drowsy = 0
66         if drowsy > 10:
67             active = 1
68             sleep = 0
69         else:
70             active = 0
71             sleep += 1
72         cv2.putText(frame, f'Drowsiness: {drowsy}', (10, 10), cv2.FONT_HERSHEY_SIMPLEX, 1, (0, 255, 0), 2)
73         cv2.imshow('Drowsy Driver Detection', frame)
74         if cv2.waitKey(1) &amp; 0xFF == ord('q'):
75             break
76     cap.release()
77     cv2.destroyAllWindows()
78
79 if __name__ == '__main__':
80     main()

```

V. Working of Project:

Drowsy driver detection systems typically use a combination of sensors and AI algorithms to monitor the driver's behavior and detect signs of drowsiness or fatigue. Here's a simplified overview of how they work:

Data Collection: Various sensors collect data about the driver and their environment.

These can include:

- Steering behavior: Monitoring the steering wheel movements for signs of erratic or drifting behavior.
- Biometric sensors: Some systems may also measure physiological indicators like heart rate or skin conductance.

Feature Extraction: Once the data is collected, relevant features are extracted from it.

For example:

- Analysis of steering behavior to detect deviations from normal driving patterns.
- Monitoring eye closure duration, frequency of blinking, and gaze direction to detect signs of drowsiness.
- Combining various data points to create a comprehensive picture of the driver's state.

Machine Learning Models: AI algorithms, often based on machine learning techniques such as deep learning, are trained using labeled data to recognize patterns associated with drowsiness or fatigue. These models can include:

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```

VI. Existing System:

Several existing systems incorporate AI for drowsy driver detection, often integrated into advanced driver assistance systems (ADAS) or built directly into vehicles. Here are a few examples:

- **Driver Monitoring Systems (DMS):** Many modern vehicles are equipped with DMS that use cameras and sensors to monitor the driver's behavior. These systems can track eye movement, head position, and even facial expressions to detect signs of drowsiness or distraction. If drowsiness is detected, the system can issue alerts to the driver or trigger other safety measures.

VII. Limitations:

AI-based drowsy driver detection systems offer promising advancements in road safety, but they come with inherent limitations. One significant challenge lies in the balance between false positives and false negatives; algorithms may inaccurately label drivers as drowsy or fail to detect actual drowsiness, compromising both user trust and safety.

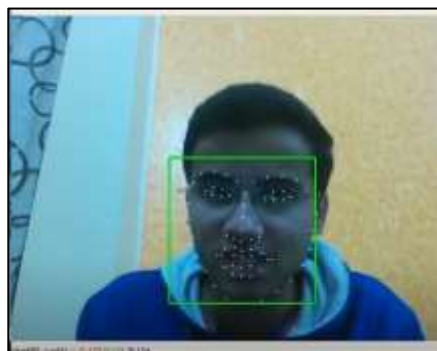


VIII. Future Direction:

The scope of a project on "AI Drowsy Driver Detection" aims to develop an AI-driven Drowsy Driver Detection System to address the pressing issue of drowsy driving, a major cause of accidents globally. By leveraging machine learning or deep learning techniques, the system will analyze facial cues, eye movements, and other relevant features to accurately detect signs of driver fatigue in real-time. The ultimate goal is to raise awareness about the dangers of driving while fatigued and to contribute to the ongoing efforts to enhance road safety through innovative technology.

IX. Advantages:

- **Early Warning System:** AI-powered drowsy driver detection can provide an early warning to the driver, potentially preventing accidents before they occur.
- **Continuous Monitoring:** Unlike traditional methods that rely on intermittent checks or subjective observations, AI systems can continuously monitor the driver's behavior, detecting signs of drowsiness in real-time.
- **Accuracy:** AI algorithms can analyze various factors such as facial expressions, eye movements, steering patterns, and vehicle dynamics with high accuracy, reducing false alarms and ensuring reliable detection.
- **Integration:** AI-based drowsy driver detection can be integrated into existing vehicle systems, such as advanced driver-assistance systems (ADAS), enhancing overall safety without requiring significant modifications.



X. Disadvantages:

- **False Positives/Negatives:** AI algorithms may occasionally produce false positives (incorrectly identifying a driver as drowsy when they are not) or false negatives (failing to detect drowsiness when it is present), which can lead to annoyance or missed warnings.
- **Privacy Concerns:** Continuous monitoring of the driver's behavior raises privacy concerns regarding the collection and storage of sensitive personal data.

- **Cost:** Implementing AI-based drowsy driver detection systems may involve significant upfront costs for research, development, and integration into vehicles, which could potentially increase the overall cost of vehicles.
- **Limited Effectiveness:** While AI can detect certain physical signs of drowsiness, it may not always accurately assess cognitive factors such as attention and decision-making, which are also crucial for safe driving.

XI. Conclusion:

Within the confront of a tireless and possibly life- debilitating issue of lazy driving, this paper has shed light on the advancement of tired driver location frameworks and their foremost importance in improving street security. Leveraging advances like computer vision and machine learning, these frameworks have come a long way in recognizing and relieving the dangers related with tiredness. Be that as it may, challenges such as minimizing untrue cautions and tending to protection concerns stay.

XII. Reference:

- [1] Drowsy Driver Detection: A Review of Methods and Technologies, by Mohamed Hegazy and Aboul Ella Hassanien (2020)
- [2] Drowsy Driver Detection Systems: A Survey, by Ehsan Moradi and Amir Hossein Rad (2019)
- [3] Driver Drowsiness Detection: A Review of Methods and Challenges, by Mohammad Reza Soleymani and Alireza Asgari (2018)