



Technological Innovations for Object Detection to Assist Blind Individuals using Deep Learning

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ABSTRACT:

A eyeless person is someone who has severe blindness that affects their capability to see and perceive the world around them. They frequently rely on other senses, similar as touch, hear, and smell, to navigate their surroundings and gather information. These people face problems in their daily work. This study aims to produce a tool that will help them work singly using different tools similar as chatbots and GTTS (Google Text to Speech). The device can capture images, identify objects, calculate the distance between objects and people, detect faces and further. It uses CNN (Convolutional Neural Network) for facial recognition. In deep learning, CNN is a type of neural network designed to reuse data from multiple layers of arrays. The system is audio enabled and makes it easier for visually disabled people to perform certain tasks singly.

Keywords: Blindness, Object Detection, CNN, Face Recognition, Chatbot.

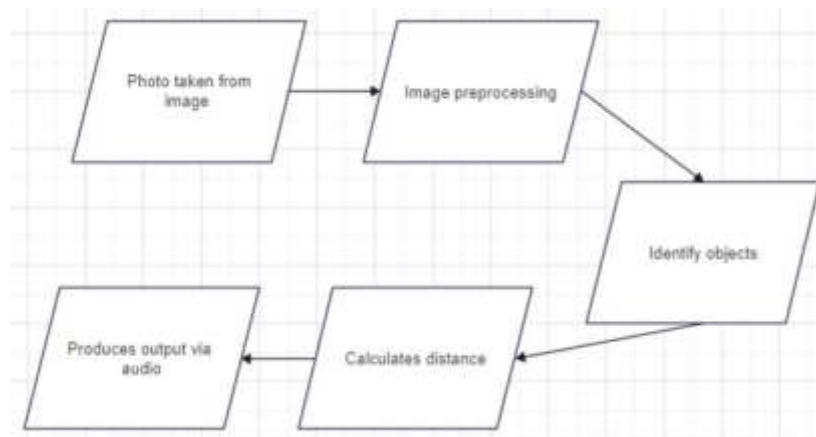
Introduction:

Technological innovations to assist blind individuals can help them overcome their challenges. One such innovation is the use of object-detection technology. Object detection technology can be used to identify objects in a scene and provide information about their location, size, and type to the user. This information can be conveyed to the user through audio feedback, making it easier for them to understand the world around them. To implement object detection technology to assist blind individuals is to use a wearable device. The device would have a built-in camera that would capture images of the user's surroundings. These images would then be processed by a system to identify any objects in the scene. The system would then provide information about the objects to the user through audio feedback.

Face recognition can help blind individuals identify people around them. By capturing and analyzing facial features, the technology can provide information about the person's identity, enabling blind individuals to recognize friends and family members. Facial recognition technology is a technology that extracts human facial features. After inputting the face image, the face function is implemented. It combines many things through specialized technology and thorough research it was developed. The principles of facial recognition technology largely consist of four parts: face image acquisition and preprocessing, face detection, facial feature extraction, and face recognition. Face detection in face recognition is used to indicate the position and size of the face in the image. Facial feature extraction is designed for the extraction of the features in faces.

A convolutional neural network (CNN) is a type of artificial intelligence (AI) that is particularly well-suited for object detection tasks. CNNs work by extracting features from images and then using those features to classify the objects in the images. Once the CNN has extracted features from the input image, it uses those features to classify the objects in the image.

Methodology:



Object detection for blind persons is a crucial technology that aims to enhance their mobility, independence, and safety by providing real-time information about their surroundings. It involves identifying and classifying objects in the user's environment using sensors and image processing algorithms.

1. Data Collection and Preprocessing

The development of an object detection system for visually impaired individuals begins with collecting a comprehensive dataset of images and their corresponding object labels. This dataset should represent the diverse environments and objects encountered in daily life, ensuring the system's generalizability.

Once acquired, the images need to be preprocessed to standardize their format and enhance the object detection algorithm's performance. This may involve:

Image Resizing: Resizing images to a uniform size to minimize computational complexity and improve detection accuracy.

Normalization: Normalizing pixel values to a common range to facilitate feature extraction and classification.

Data Augmentation: Artificially expanding the dataset by applying techniques like flipping, rotating, and cropping images to increase the algorithm's robustness to variations in object appearance and pose.

2. Object Detection Algorithm Selection

The choice of object detection algorithm depends on factors such as accuracy, computational efficiency, and the specific requirements of the assistive device. Convolutional Neural Networks (CNNs) have emerged as a prominent approach due to their ability to learn complex patterns and features from images, achieving high detection accuracy.

Other object detection algorithms that may be considered include:

Single Shot MultiBox Detector (SSD): SSD generates multiple bounding boxes at different scales and aspect ratios, improving detection accuracy for objects of varying sizes.

You Only Look Once (YOLO): YOLO divides the input image into a grid and predicts bounding boxes and object classes for each grid cell, achieving fast detection speeds.

3. Algorithm Training

The selected object detection algorithm needs to be trained on the preprocessed dataset to learn the patterns and features that distinguish different objects. The object detection algorithm is trained on a large dataset of images that have been labeled with the objects they contain. The algorithm learns to identify the objects in the images by analyzing the patterns and features in the pixels.

4. Integration with Assistive Devices

The trained object detection algorithm needs to be integrated into an assistive device that can provide real-time feedback to the user. The device should be lightweight, portable, and easy to operate, considering the needs of visually impaired individuals.

The device's functionality may include:

Conclusion:

This study's main objective is to develop a system that helps persons with vision impairments to freely navigate their surroundings. In the developed system, object identification and distance calculating are the two main components. The object identification system will provide the names of the items. The user is supposed to be guided by the distance sensing system. The project bases its object detection and distance calculating on Yolo3 techniques. It is used for detecting objects in front of the user and measuring the separation between the object and the visually impaired individual. The quickest was to be Yolo3, followed by SSD. Select Yolo3 if you need to evaluate a live video feed. SSD, however, provides a decent balance between accuracy and speed. CNN is a neural network used for face recognition. Different datasets are applied on this network. LFW dataset results more accuracy followed by CASIA face V5 and MTFLL.

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