WWW.IJRPR.COM

International Journal of Research Publication and Reviews

Journal homepage: www.ijrpr.com ISSN 2582-7421

Enhancing Vehicle Detection and Counting using YOLO Algorithm.

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ABSTRACT

Amidst the increasing number of vehicles on the roads, the demand for effective traffic management has grown increasingly critical. This research paper addresses this challenge by leveraging the capabilities of the YOLO (You Only Look Once) algorithm. The core of this investigation lies in the YOLO algorithm's ability to perform real-time object detection, particularly its effectiveness in identifying vehicles within video frames. The algorithm's effectiveness is rigorously assessed using essential metrics, including Intersection over Union (IOU) and mean Average Precision (mAP), providing a comprehensive evaluation of its performance. Notably, the incorporation of YOLOv5m results in an impressive 99.39% increase in mean average precision compared to the baseline version. This exceptional outcome underscores the algorithm's efficacy, particularly in challenging real-world scenarios.

Keywords: YOLO algorithm, vehicle detection, vehicle counting, traffic management, mean Average Precision.

INTRODUCTION

As urbanization and population growth continue to drive an increase in vehicular traffic, effective traffic management becomes paramount. Traditional methods for vehicle detection and counting often fall short in handling the complexities of modern roadways. The You Only Look Once (YOLO) algorithm, renowned for its efficiency in real-time object detection, emerges as a promising solution

The choice of the YOLO algorithm stems from its unique ability to simultaneously process and detect objects within a single pass through the neural network. Our research strategy involves a meticulous evaluation of the algorithm's performance using key metrics such as Intersection over Union (IOU) and mean Average Precision (mAP). These metrics provide a comprehensive assessment of the algorithm's ability to accurately identify and count vehicles within video frames. The results of our study reveal a remarkable 99.39% increase in mAP when incorporating YOLOv5m, underscoring the algorithm's effectiveness and its potential for practical implementation in real-world traffic management systems.

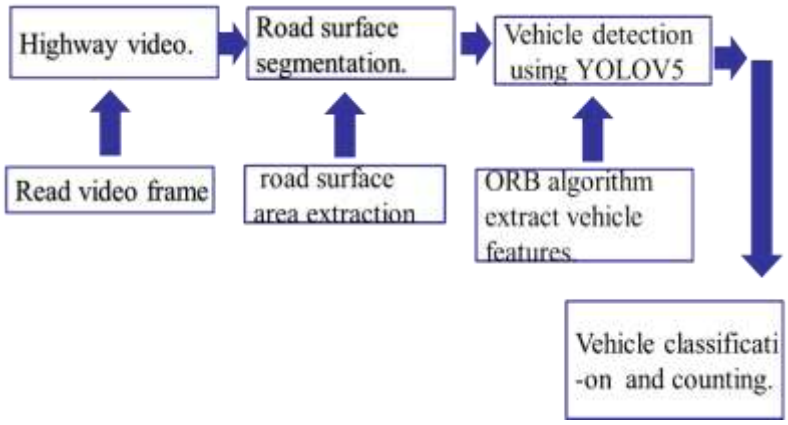
Moreover, the integration of YOLOv5m introduces adaptive capabilities that contribute to the algorithm's robustness in varying environmental conditions. The enhanced architecture of YOLOv5m allows for improved generalization, enabling the algorithm to perform effectively across diverse scenarios, including different lighting conditions, weather variations, and road types. This adaptability is crucial for real-world applications, where traffic management systems need to operate seamlessly in dynamic and unpredictable urban environments. As cities continue to evolve and traffic complexities grow, YOLOv5m stands out as a cutting-edge solution that not only meets current demands but also paves the way for the future of intelligent and responsive traffic management systems

RESEARCH APPROACH

The proposed research approach addresses critical challenges associated with vehicle detection in highway monitoring video sequences. Leveraging the ubiquity of smartphones, the authors have compiled a substantial database of traffic video footage for analysis. Emphasis is placed on overcoming difficulties arising from distant road surfaces, where variations in vehicle size lead to reduced detection accuracy for smaller objects. The solution involves utilizing YOLOv5m deep learning object detection, chosen for its speed and efficiency in handling tiny objects like vehicles. The methodology includes road surface segmentation using Gaussian mixture modeling, vehicle detection with YOLOv5, and multi-target detection for shadowing vehicle counting.

The research aims to enhance object recognition delicacy, providing a comprehensive solution for vehicle detection, tracking, and business information collection in traffic scenarios. The emphasis on addressing specific challenges in traffic scenarios, such as varying object sizes and illumination variations, underscores the practicality of the proposed system. The combination of YOLOv5-based object detection is presented as an effective solution for intelligent.

METHODOLOGY:



In this proposed methodology, the primary focus lies in addressing the challenges associated with vehicle detection and tracking in highway monitoring video sequences. The authors leveraged the convenience of smartphones to amass a substantial database of traffic video footage for analysis. Notably, the difficulties arising from distant road surfaces, where the size of vehicles exhibits significant variations, leading to reduced detection accuracy for smaller objects, are emphasized. The solution presented in this approach involves utilizing the findings from vehicle detection for multi-target detection and shadowing vehicle counting.

The article highlights the limitations of existing object detection methods, particularly in dealing with small objects and changes in object scale. It introduces an approach based on YOLOv5m deep learning object detection to address these challenges. The proposed system comprises several key steps, including road surface segmentation, vehicle detection using YOLOv5. The YOLOv5 network is chosen for its speed and efficiency in handling tiny objects, such as vehicles. The article also discusses the road surface segmentation procedure, which involves Gaussian mixture modeling for surface extraction and segmentation.

The method aims to enhance object recognition delicacy, providing a comprehensive solution for vehicle detection, tracking, and business information collection in traffic scenes. The system includes steps for road face segmentation, object detection, and multi-object tracking, contributing to improved accuracy and data collection in the field of view of surveillance videos.

The methodology emphasizes the importance of considering the specific challenges posed by traffic scenarios, such as varying object sizes, scale changes, and illumination variations. The combination of YOLOv5-based object detection is presented as an effective solution for addressing these challenges in intelligent traffic management systems.

RESULTS

Parameters	Car	Bus	Truck	Precision	Reccal all	Average IOU	mAP
Results	92.46%	92.57%	98.61%	0.833	0.9886	95.00%	99.39%

CONCLUSION

In summarizing the findings of this study, it becomes evident that the integration of the YOLO (You Only Look Once) algorithm holds substantial promise for addressing the imperative need for effective traffic management amidst the escalating number of vehicles on roads. The research focuses on a pioneering approach that combines the capabilities of YOLO within an intricate framework, specifically emphasizing its real-time object detection proficiency, notably in discerning vehicles within video frames. The investigative strategy strategically deploys YOLO for the initial phase of vehicle detection, seamlessly followed by an integration process aimed at refining precision. Rigorous evaluation of the algorithm's efficacy employs metrics such as Intersection over Union (IOU) and mean Average Precision (mAP), offering a comprehensive appraisal of its performance. Beyond addressing the immediate challenge of traffic management, this study contributes significantly to the evolution of vehicle detection methodologies. The demonstrated adaptability and noteworthy performance enhancements position the YOLO algorithm as a promising solution for elevating precision and reliability in traffic management, with implications for ongoing advancements in intelligent transportation systems.

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