



Stability Study of Thin Rectangular C-S-C-F Plate Under Buckling Load Using 3rd Order Functionals

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ABSTRACT

The research centers on the buckling effect of rectangular Clamped-Simple-Clamped- Fixed plate Isotropic plate. This was done using 3rd energy Functional. The CiSiCiFi plate was considered as the direct independent plate. That means the material properties like the flexural rigidity, poisson ratio and young elastic modulus of elasticity are the same round about the shape of the object. The shape functions were first derived and then the various integral values of the differentiated shape functions, of the various boundary conditions were all gotten. Based on the derived results, the stiffness coefficients of the various boundary arrangements were also formulated. Upon further minimizations, the Third order strain energy equation was derived and further expansion Third order strain energy equation gave rise to the Third Order Overall Potential Energy Functional. The Third Order Overall Potential Energy Functional, with respect to the amplitude was further integrated and this gave a result known as the Lead equation. Further minimization of the Lead equation gave rise to the Vital buckling load equations. Next to this was the formulation of the non-dimensional buckling load parameters which, m/n ranging from 1.0 to 2.0, and considering it at the interval of 0.1. The relationship of the non-buckling load parameters against the various aspect ratios was shown on the graph.

Key words:

- ❖ Overall Potential Energy Functional,
- ❖ Lead Equation,
- ❖ Vital Buckling load

Introduction

A plate element can be considered as a structural element having straight or curves boundaries, and also possessing three dimensions known as the primary, secondary and tertiary dimension. The tertiary dimension also known as the plate thickness are usually very small compared to other dimensions. The isotropic rectangular CiSiCiFi plate have all their material properties in all directions as the same and so they classified as direction independent element. Stability analysis sometimes is referred to as the plate buckling has been a subject of study in solid structural mechanics for a long time now. Although the buckling analysis of rectangular plates has received the attention of many researchers for several centuries Prior to this time, other researchers have gotten solution using both the Second and Fourth the Order energy functional for Buckling of plate. None of the scholars have any work on buckling of plate using Third order energy functional and so the resolution of the buckling tendency of CLAMPED SIMPLE CLAMPED FIXED isotropic plate using third order energy functional is the gap the work tends to fill. The plates arrangement can be as shown

1.1 Formulation of The Buckling Load Equation.

Overall potential energy, O_p is the summation of Strain energy, ϵ and External Work, E_w given as: $O_p = \epsilon + E_w$ 1i

To derive the strain energy, ϵ the product of normal stress and normal strain in x direction is considered as

$$S_x \delta_x = \frac{Ez^2}{1-\mu^2} \left(\left[\frac{\partial^2 fk}{\partial x^2} \right]^2 + \mu \left[\frac{\partial^2 fk}{\partial x \partial y} \right]^2 \right) \quad 1ii$$

while their product in y direction is considered as

$$S_y \delta_y = \frac{Ez^2}{1-\mu^2} \left(\left[\frac{\partial^2 fk}{\partial y^2} \right]^2 + \mu \left[\frac{\partial^2 fk}{\partial x \partial y} \right]^2 \right) \quad 1iii$$

And finally the product of the in-plane shear stress and in-plane shear

strain is given as: $\tau_{xy}\gamma_{xy} = 2 \frac{Ez^2(1-\mu)}{(1-\mu^2)} \left[\frac{\partial^2 fk}{\partial x \partial y} \right]^2$ 1iv

adding all together gives

$$\delta_x \delta_x + \delta_y \delta_y + \tau_{xy}\gamma_{xy} = \frac{Ez^2}{1-\mu^2} \left(\left[\frac{\partial^2 fk}{\partial x^2} \right]^2 + 2 \left[\frac{\partial^2 fk}{\partial x \partial y} \right]^2 + \left[\frac{\partial^2 fk}{\partial y^2} \right]^2 \right)$$
 1v

But $\epsilon = \frac{1}{2} \iint_{xy} \bar{\epsilon} \, dx dy$ where $\bar{\epsilon} = \frac{Ez^2}{1-\mu^2} \int \left(\left[\frac{\partial^2 fk}{\partial x^2} \right]^2 + 2 \left[\frac{\partial^2 fk}{\partial x \partial y} \right]^2 + \left[\frac{\partial^2 fk}{\partial y^2} \right]^2 \right)$ 1vi

Upon minimisation of the expressions above, the third order strain energy equation is given as

$$\epsilon = \frac{G}{2} \int_0^n \int_0^m \left(\frac{\partial^3 fk}{\partial x^3} \cdot \frac{\partial fk}{\partial x} + 2 \frac{\partial^3 fk}{\partial x \partial y^2} \cdot \frac{\partial fk}{\partial x} + \frac{\partial^3 fk}{\partial y^3} \cdot \frac{\partial fk}{\partial y} \right) dx dy$$
 2i

with the external load as $v = -\frac{Bx}{2} \int_0^n \int_0^m \left(\frac{\partial^3 k}{\partial x} \right)^2 dx dy$ 2ii

The third order total potential energy functional is expressed mathematically as

$$O_p = \frac{G}{2} \int \int \left(\frac{\partial^3 fk}{\partial x^3} \cdot \frac{\partial fk}{\partial x} + 2 \frac{\partial^3 fk}{\partial x^2 \partial y} \cdot \frac{\partial fk}{\partial y} + \frac{\partial^3 fk}{\partial y^3} \cdot \frac{\partial fk}{\partial y} \right) dx dy - \frac{Bx}{2} \int \int \frac{\partial^2 fk}{\partial x^2} dx dy$$
 2ii

Rearranging the total potential energy equation in terms of non dimensional parameters, the buckling load equation is gotten as

$$B_x = \frac{\frac{G}{a^2} \int_0^1 \int_0^1 \left(\left[\frac{\partial^3 fk}{\partial j^3} \right] \frac{\partial fk}{\partial j} + 2 \frac{1}{p^2} \left[\frac{\partial^3 fk}{\partial j \partial i^2} \right] \frac{\partial fk}{\partial i} + \frac{1}{p^4} \left[\frac{\partial^3 fk}{\partial i^3} \right] \frac{\partial fk}{\partial i} \right) dj di}{\int_0^1 \int_0^1 \left(\frac{\partial^3 k}{\partial j} \right)^2 dj di}$$
 2iii

1.2 Derivation of Shape Function

Three major support conditions were considered, in the derivation of the shape functions and they namely Fixed support which was denoted as Fi, Simple support which is denoted as Si and Clamped support which is denoted as Ci. For Simple support condition, the deflection equation F and the 2nd order derivative of the deflection equation F², were equated to zero and simultaneous equations were formed by considering J = 0 at the left hand support for X axis and I = 1 at the right. Also considering the top as J = 1 and I = 1 at the bottom support for the Y axis. For the Clamped support condition, the deflection equation, F and 1st order derivative of the deflection equation, F¹, were equated to zero and simultaneous equations were formed by considering J = 0 at the top support and I = 0 at the bottom support for the Y axis, while at the Right hand support, J = 1 while I = 1 at the left support for X axis. These equations were solved simultaneously to obtain the various values of the primary and secondary dimensions (n₁, m₁, n₂, m₂, n₃, m₃, n₄ and m₄) for the CiSiCiFi plate element. Where J and I are non-dimensional axis parallel to X and Y axis respectively as earlier explained.

1.3 Formulation of Shape Function For Clamped-Simple-Clamped-Fixed Plate



Fig 1a Isotropic Rectangular CiSiCiFi Plate

The case of horizontal Direction (X- X axis)



Fig 1b Simple-Fixed Support on x-x axis

Considering the X- X axis

But $F_x = n_0 + n_1 J + n_2 J^2 + n_3 J^3 + n_4 J^4 + n_5 J^5$ 6

$F_x^1 = n_1 + 2n_2 J + 3n_3 J^2 + 4n_4 J^3 + 5n_5 J^4$ 7

$F^2 = 2n_2 + 6n_3 J + 12n_4 J^2 + 20n_5 J^3$ 8

$F^3 = 6n_3 + 24n_4 J + 60n_5 J^2$ 9

Introducing the boundary conditions, reduces the Equations 6-9 as

At the left support, $J = 0$

When $F_x = 0$

$$F_x = 0 = n_0 + 0 + 0 + 0 + 0 \quad 10$$

$$n_0 = 0$$

$$\text{Also when } f_x'' = 0 \quad 11$$

$$F_x'' = 0 = 2n_2 + 0 + 0 + 0 \quad 12$$

$$2n_2 = 0 \quad 13$$

$$n_2 = 0 \quad 14$$

At the right support, $J = 1$

$$F_x' = n_1 + 0 + 3n_3 + 4n_4 + 5n_5 = -\frac{2n_5}{3} \quad 15$$

Further simplifying Equation 15 gives

$$n_1 = -\frac{2n_5}{3} - 3n_3 - 4n_4 - 5n_5 \quad 16$$

Also for the second derivative of the Deflection,

$$F_x'' = 0 = 0 + 6n_3 + 12n_4 + 20n_5 \quad 17$$

Making n_3 the subject gives

$$n_3 = \frac{-12n_4 - 20n_5}{6} \quad 18$$

$$n_3 = \frac{-10n_5}{3} - 2n_4 \quad 19$$

For the third derivative of the Deflection,

$$F_x''' = 0 = 6n_3 + 24n_4 + 60n_5 \quad 20$$

$$F_x''' = 0 = 6n_3 + 24n_4 + 60n_5 \quad 21$$

$$n_3 = \frac{-60n_5 - 24n_4}{6} \quad 22$$

Comparing Equation 19 and 22 gives

$$\frac{-10n_5}{3} - 2n_4 = \frac{-60n_5 - 24n_4}{6} \quad 23$$

Bringing the like terms together and further simplifying gives

$$n_4 = \frac{-10n_5}{3} \quad 24$$

But substituting Equation 24 into Equation 22 gives

$$n_3 = \frac{-60n_5 - 24\left(\frac{-10n_5}{3}\right)}{6} \quad 25$$

Further simplification gives

$$n_3 = \frac{10n_5}{3} \quad 26$$

Putting Equations 25 and 26 into Equation 16 gives

$$n_1 = -\frac{2n_5}{3} - 3\left(\frac{10n_5}{3}\right) - 4\left(\frac{-10n_5}{3}\right) - 5n_5 \quad 27$$

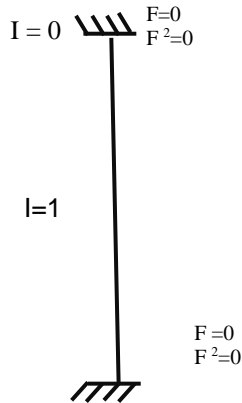
$$n_1 = -\frac{7n_5}{3} \quad 28$$

$$\text{Recall that } F_x = n_0 + n_1J + n_2J^2 + n_3J^3 + n_4J^4 + n_5J^5 \quad 29$$

Putting the derived values into Equation 29 gives

$$F_x = n_5 \left(-\frac{7J}{3} + \frac{10J^3}{3} - \frac{10J^4}{3} + J^5 \right) \quad 30$$

The case of horizontal Direction (Y- Y axis)



$$F_y = m_0 + m_1 I + m_2 I^2 + m_3 I^3 + m_4 I^4 \tag{31}$$

The first derivative on Y axis gives

$$F_y^1 = m_1 + 2 m_2 I + 3 m_3 I^2 + 4 m_4 I^3 \tag{32}$$

Considering the boundary conditions on the clamped ends gives

At I = 0,

$$F_y = 0 = m_0 + 0 + 0 + 0 + 0 \tag{33}$$

$$\text{Leaving } m_0 = 0 \tag{34}$$

Also

$$F_y^1 = m_1 + 0 + 0 + 0 + 0 \tag{35}$$

$$m_1 = 0 \tag{36}$$

At I = 1,

$$F_y = 0 = 0 + 0 + m_2 + m_3 + m_4 \tag{37}$$

$$m_2 + m_3 = - m_4 \tag{38}$$

$$F_y^1 = 0 = 0 + 2m_2 + 3m_3 + 4m_4 \tag{39}$$

$$m_2 = - m_3 - m_4 \tag{40}$$

Putting Equation 40 into the first derivatives gives

$$F_y^1 = 0 = 0 + 2(- m_3 - m_4) + 3m_3 + 4m_4 \tag{41}$$

Opening the bracket gives

$$m_3 + 2m_4 = 0 \tag{42}$$

$$\text{That means } m_3 = -2m_4 \tag{43}$$

Putting it back into Equation 40 gives

$$m_2 = - (-2m_4) - m_4 \tag{44}$$

$$m_2 = +m_4 \tag{45}$$

Substituting the derived values into Equation 30 gives

$$F_y = m_4 I^2 - 2m_4 I^3 + m_4 I^4 \tag{46}$$

$$F_y = m_4 (I^2 - 2I^3 + I^4) \tag{47}$$

$$\text{That means } F = F_x * F_y = m_4 (I^2 - 2I^3 + I^4) * n_5 \left(-\frac{7I}{3} + \frac{10I^3}{3} - \frac{10I^4}{3} + J^5 \right) \tag{48}$$

$$fk = f_{k_x} * f_{k_y} = m_4 n_5 (I^2 - 2I^3 + I^4) \left(-\frac{7I}{3} + \frac{10I^3}{3} - \frac{10I^4}{3} + J^5 \right) \tag{49}$$

$$\text{The shape function is give as } (I^2 - 2I^3 + I^4)\left(-\frac{7I}{3} + \frac{10J^3}{3} - \frac{10J^4}{3} + J^5\right) \quad 50$$

Equation 50 is further differentiated at different stages, from where the stiffness coefficients were derived. These includes

$$\frac{\partial f_k}{\partial J} = (I^2 - 2I^3 + I^4)\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) \quad 51$$

$$\frac{\partial^2 f_k}{\partial J \partial I} = \left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right)(2I - 6I^2 + 4I^3) \quad 52$$

$$\frac{\partial f_k}{\partial J \partial I^2} = \left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right)(2 - 12I + 12I^2) \quad 53$$

$$\frac{\partial^2 f_k}{\partial J^2} = (I^2 - 2I^3 + I^4)\left(-\frac{7}{3} + 60J - 10 * 4J^2 + 20J^3\right) \quad 54$$

$$\frac{\partial^3 f_k}{\partial J^3} = (I^2 - 2I^3 + I^4)(60 - 80J + 60J^2) \quad 55$$

also

$$\frac{\partial f_k}{\partial I} = (2I - 6I^2 + 4I^3)\left(-\frac{7I}{3} + \frac{10J^3}{3} - \frac{10J^4}{3} + J^5\right) \quad 56$$

$$\frac{\partial^2 f_k}{\partial I^2} = (2 - 12I + 12I^2)\left(-\frac{7I}{3} + \frac{10J^3}{3} - \frac{10J^4}{3} + J^5\right) \quad 57$$

$$\frac{\partial^3 f_k}{\partial I^3} = (-12 + 24I)\left(-\frac{7I}{3} + \frac{10J^3}{3} - \frac{10J^4}{3} + J^5\right) \quad 58$$

Integrating the product Equation 55 by 51 give the first stiffness coefficient. That

is

$$sc_1 = \int_0^1 \int_0^1 \frac{\partial^3 f_k}{\partial J^3} * \frac{\partial f_k}{\partial J} dIdJ \quad 59$$

$$sc_1 = \int_0^1 \int_0^1 \left[(I^2 - 2I^3 + I^4)(60 - 80J + 60J^2) * (I^2 - 2I^3 + I^4)\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) \right] dIdJ \quad 60$$

bringing the like terms together gives

$$= \int_0^1 \int_0^1 \left[(I^2 - 2I^3 + I^4)(I^2 - 2I^3 + I^4) * (60 - 80J + 60J^2)\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) \right] dIdJ \quad 60a$$

multiplying them gives

$$= \int_0^1 \int_0^1 \left[(I^2(I^2 - 2I^3 + I^4) - 2I^3(I^2 - 2I^3 + I^4) + I^4(I^2 - 2I^3 + I^4)) * \left(60\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) - 80J\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) + 60J^2\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right)\right) \right] dIdJ \quad 60b$$

further minimization yields

$$sc_1 = 0.789 * 0.8296$$

$$= 0.65455$$

also integrating the product Equation 53 by 51 give the second stiffness coefficient.

That is

$$sc_2 = \int_0^1 \int_0^1 \frac{\partial^3 f_k}{\partial J \partial I^2} * \frac{\partial f_k}{\partial J} dIdJ \quad 61$$

$$sc_2 = \int_0^1 \int_0^1 \left[\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right)(2 - 12I + 12I^2) * (I^2 - 2I^3 + I^4)\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) \right] dIdJ \quad 62$$

Bring the like terms together gives

$$\int_0^1 \int_0^1 \left[(2 - 12I + 12I^2)(I^2 - 2I^3 + I^4) * \left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right)\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) \right] dIdJ \quad 62a$$

Multiplying the like terms gives

$$\int_0^1 \int_0^1 \left[(2(I^2 - 2I^3 + I^4) - 12I(I^2 - 2I^3 + I^4) + 12I^2(I^2 - 2I^3 + I^4)) * \left(-\frac{7}{3}\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) + 30J^2\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) - \frac{40J^3}{3}\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) + 5J^4\left(-\frac{7}{3} + 30J^2 - \frac{40J^3}{3} + 5J^4\right) + 5J^4\right) \right] dIdJ \quad 62b$$

$$sc_2 = 0.01891 * 2.11599$$

$$= 0.0400137$$

Furthermore integrating the product Equation 58 by 56 give the third stiffness coefficient. That is

$$sc_3 = \int_0^1 \int_0^1 \frac{\partial^3 f_k}{\partial I^3} * \frac{\partial f_k}{\partial I} dIdJ \quad 63$$

$$sc_3 = \int_0^1 \int_0^1 \left[(-12 + 24I)\left(-\frac{7I}{3} + \frac{10J^3}{3} - \frac{10J^4}{3} + J^5\right) * (2I - 6I^2 + 4I^3)\left(-\frac{7I}{3} + \frac{10J^3}{3} - \frac{10J^4}{3} + J^5\right) \right] dIdJ \quad 64$$

$$sc_3 = 0.0001579 * 3.77781$$

$$= 0.00059651$$

and finally integrating the product Equation 51 by 51 give the sixth stiffness coefficient. That is

$$sc_6 = \int_0^1 \int_0^1 \left(\frac{\partial f_k}{\partial j} * \frac{\partial f_k}{\partial l} \right) dl dj \tag{63}$$

$$sc_6 = \int_0^1 \int_0^1 \left[(l^2 - 2l^3 + 14) \left(-\frac{7}{3} + 30j^2 - \frac{40j^3}{3} + 5j^4 \right) * (l^2 - 2l^3 + 14) \left(-\frac{7}{3} + 30j^2 - \frac{40j^3}{3} + 5j^4 \right) \right] dl dj \tag{64}$$

Collecting the like terms together gives

$$= \int_0^1 \int_0^1 \left[(l^2 - 2l^3 + 14) * (l^2 - 2l^3 + 14) \left(-\frac{7}{3} + 30j^2 - \frac{40j^3}{3} + 5j^4 \right) \left(-\frac{7}{3} + 30j^2 - \frac{40j^3}{3} + 5j^4 \right) \right] dl dj \tag{65}$$

Opening the brackets gives

$$= \int_0^1 \int_0^1 \left[(l^2 (l^2 - 2l^3 + 14) - 2l^3 (l^2 - 2l^3 + 14) + 14(l^2 - 2l^3 + 14)) * \left(-\frac{7}{3} \left(-\frac{7}{3} + 30j^2 - \frac{40j^3}{3} + 5j^4 \right) + 30j^2 \left(-\frac{7}{3} + 30j^2 - \frac{40j^3}{3} + 5j^4 \right) - \frac{40j^3}{3} \left(-\frac{7}{3} + 30j^2 - \frac{40j^3}{3} + 5j^4 \right) + 5j^4 \left(-\frac{7}{3} + 30j^2 - \frac{40j^3}{3} + 5j^4 \right) \right) \right] dl dj \tag{65b}$$

$$sc_6 = 0.018111 * 0.8478$$

$$= 0.0153545$$

Reducing Equation 2iii in terms of the stiffness coefficients gives

$$B_x = \frac{D(sc_1 + 2\frac{1}{p^2}sc_2 + \frac{1}{p^4}sc_3)}{sc_6 a^2} \tag{65}$$

Substituting the real values in to Equation 65 gives

$$B_x = \frac{D(0.65455 + 2\frac{1}{p^2}0.0400137 + \frac{1}{p^4}0.00059651)}{0.0153545a^2} \tag{66}$$

RESULTS AND DISCUSSION.

The results for the stiffness coefficients and the critical buckling load coefficients were derived. The critical buckling load coefficients were considered at different aspect ratios. The first table represents the values of the stiffness coefficients while the other contains the critical buckling coefficients for the aspect ratio of m/n, both for the previous and present study. The values of the aspect Ratios ranges from 2.0 to 1.0 with arithmetic increase of 0.1. From the values generated in the tables, it was observed that as the aspect ratio increases from 1.0 to 2.0, the critical buckling load decreases. This occurred both in the present and previous results.

Table 1.1 Stiffness Coefficients from Previous researchers

Stiffness coefficients, sc	Derived values
sc ₁	0.67096
sc ₂	0.04043
sc ₃	0.006047
sc ₆	0.0159444

Table 1.2 Stiffness Coefficients from Present Work

Stiffness coefficients, sc	Derived values
sc ₁	0.65455
sc ₂	0.0400137
sc ₃	0.0059651
sc ₆	0.0153545

Table 1.3 Critical buckling load values for CSCF Plate from Previous/Present.

m/n		2	1.9	1.8	1.7	1.6
B		43.9346	44.0759	44.2415	44.4373	44.6711
B _x	Previous	43.3728	43.5151	43.6826	43.8814	44.1201
	Present	43.9346	44.0759	44.2415	44.4373	44.6711

Table 1.3 cont'd.

m/n		1.5	1.4	1.3	1.2	1.1	1
B		44.9533	45.2985	45.7268	46.2674	46.9632	47.88
$B_s \frac{G}{h^2}$	Previous	44.4101	44.7674	45.2148	45.7859	46.5315	47.5319
	Present	44.9533	45.2985	45.7268	46.2674	46.9632	47.88

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