



TIME DOMAIN ANALYSIS OF REACTIVE AND OPTIMAL MODULATION FOR ISOLATED DUAL BRIDGE DC/DC CONVERTERS

Damini Gadde¹, Dr. Tutakne²

¹M.Tech 3rd sem (PEPS), Wainganga college of Engineering and Technology, damini.gadde@gmail.com

²Wainganga college of Engineering and Technology

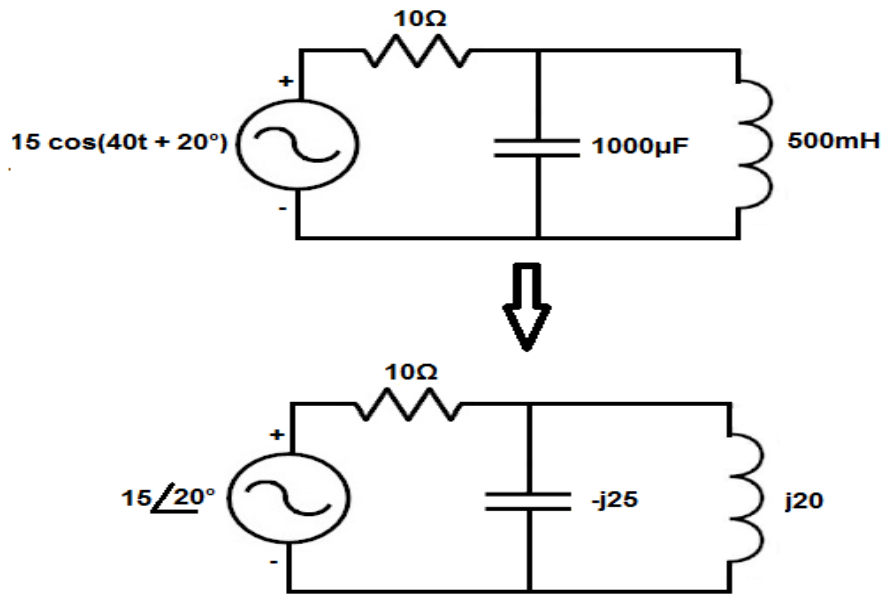
ABSTRACT

This letter discusses the reactive components and the power factor of dual-active-bridge converters under triple-phase-shift modulation. Different from previous methods based on backflow power integral or Fourier series expansion, this letter presents a straightforward analysis and categories of reactive current through time-domain analysis and then gives a unified time-domain definition of reactive current, reactive power, and power factor. Compared with all the previous definitions, the expressions of reactive components and power factors are much more concise and of profound physical meaning. On this basis, specific calculations of reactive power and power factor are derived for all practical voltage patterns and an optimal global power factor phase shift modulation is proposed to improve the power factor on both bridges. At last, the effectiveness of analysis and proposed modulation were validated using a 500-W laboratory prototype. The results showed efficiency improvements compared to other optimal power factor modulation strategies

1. INTRODUCTION

ISOLATED dual active bridge (DAB) converters are gaining more attention for the merits of simple structure, easy to control, and high power density. Single-phase-shift (SPS) modulation only utilizes the outer phase shift between high frequency (HF) voltages as control variable, and suffers huge HF current if the voltage gain is not matched with the high frequency transformer (HFT) turns ratio [1]. Numerous modulation strategies with more modulation parameters have been proposed in literatures to deal with this problem, such as extended-phase-shift (EPS) modulation in [2] and [3], dual-phase-shift (DPS) modulation in [4], and triple-phase-shift (TPS) modulation strategies for different optimization goals [5]–[8]. In order to study and quantify the effect of different modulation strategies, many works focused on the reactive power or the power factor in the HF link. Concept of reactive power was originally proposed in [4]. Based on this definition, the reactive power equals the flow back power and is generated by the phase difference between the HF voltage and the HF current on primary bridge. However, the physical significance is not clear as the HF components are non sinusoidal. The current stress was used to indicate the reactive power in [8], which lacked direct linking. Authors in [9]–[11] defined the reactive power Centered)

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and the power factor based on Fourier series expansion. The reactive power was generated by all the HF components and was express din form of infinite series, whose summation was hard to be derived. So [9] and [10] only came up with modulation strategies to minimize the fundamental reactive power of the primary bridge. Besides, the se modulation strategies turned out to be special cases of EPS modulation and failed to cover the whole power range. Further in [11], authors considered up to the seventh order harmonics and adopted particle swarm optimization to obtain an optimized TPS modulation strategies. Still the higher frequency components were neglected and the optimization procedure was complex. Therefore, previous researches were difficult for practical use in the modulation parameters optimization and failed to present the straight forward influences of modulation parameters on re active power and power factor. Moreover, the primary bridge and the secondary bridge are equally important in the power transfer, but previous studies only considered the reactive power of the primary bridge. To clearly address reactive current and reactive power in DAB converters under TPS modulation, this letter presents a time domain analysis of HF current to derive unified analytical expressions of reactive current, reactive power, and power factor. On this basis, an optimal TPS modulation scheme is proposed to improve the power factor on both bridges and increase converter efficiency.

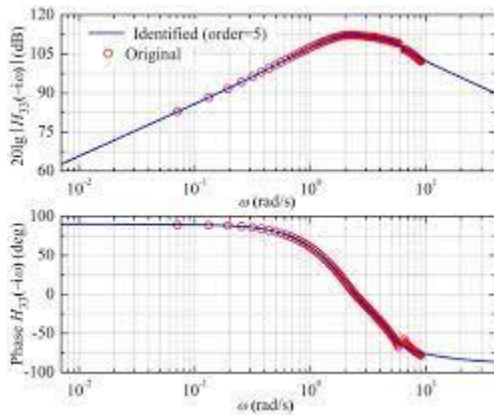
TIME DOMAIN ANALYSIS OF REACTIVE COMPONENTSSA. Operation Principle of DAB With TPS Modulation Scheme Fig. 1 shows the circuit configuration and the equivalent circuit of a DAB converter. The converter consists of two full-bridges connected through an HFT. Turns ratio of the HFT is $n:1$. L_1 and L_2 include the leakage inductance of HFT and the additional inductance. The dc voltages of the primary bridge and the secondary bridge are U_1 and U_2 , respectively. The full bridges work at frequency f_s , and their voltage e outputs are u_{AB} and u_{CD} . DAB can be equivalent to two square voltage sources connected through the equivalent inductance, where all the parameters are refer red to the primary side.

Fig. 2 shows the steady-state operation waveforms of TPS modulation. Power transfers from primary bridge to secondary bridge and equals P . The inner phase shift of the primary bridge is D_1 , and u_{AB} is a square wave with duty cycle of $(1 - D_1)/2$. Similarly, the inner phase shift of the secondary bridge is D_2 , and duty cycle of u_{CD} is $(1 - D_2)/2$. D_1 and D_2 are commonly limited within $[0, 1]$. The outer phase shift between u_{AB} and u_{CD} is D_0 , and is generally limited within $[-0.5, 0.5]$. All the phase shift parameters have influences on the HF current i_L and power transfer characteristics, but the magnitude and the current stress of i_L can be reduced through appropriate combinations .The voltage gain M and root-mean-square value of HF components are defined as $M = nU_2/U_1$, $U_{AB} = \text{RMS}(u_{AB}) = U_1 \sqrt{1 - D_1}$, $I_L = \text{RMS}(i_L)$, $U_{CD} = \text{RMS}$

Time Domain Analysis of Reactive Current In Fig. 2, the instant power is negative between t_1 and t_2 or between t_6 and t_7 , so i_L during this time interval was usually defined as the circling current and the power during this time interval was defined as the reactive power in [4] and [5]. However, this definition is narrow to depict the influence of voltage mismatch and phase shift modulation, so a new analysis of the reactive current is proposed. U_{AB} keeps zero from t_4 to t_6 , and the primary bridge cannot provide any active power during this time interval. However, i_L is not always equal to zero from t_4 to t_6 . Thus, i_L does not transfer any power from primary bridge but still causes conduction losses. So this part of i_L is defined as the freewheeling reactive current . u_{AB} equals U_1 from t_1 to t_4 , and the primary bridge transfers power during this time interval. The average value of i_L between t_1 and t_4 is $I_{ave1} = P(1 - D_1)/U_1$. (2) If i_L is ideally even and equals I_{ave1} between t_1 and t_4 , the converter can transfer the same amount of power with the minimum current stress and current rms value. The rest part of i_L during this interval fluctuate zero and does not transfer active power but increases both conduction and switching losses. Thus, it is defined as the fluctuant reactive current. It is worth mentioning that the circling current is included in the fluctuant reactive current. $(u_{CD}) = U_2 \sqrt{1 - D_2}$.

Based on analysis above, the ideal current for primary bridge should have the same shape as u_{AB} , A sip 1 shown in Fig. 2. Generally, i_{p1} transfers the same amount of power as i_L , but with the minimum RMS value and current stress, and is defined as the active part of i_L . The expression of i_{p1} and its RMS value are $i_{p1} = P/U_{AB} \cdot u_{AB}$, $I_{p1} = \text{RMS}(i_{p1}) = P/U_{AB}$. (3) The rest part of i_L contains freewheeling reactive current and fluctuate reactive current, and is the overall reactive current of the primary bridge $i_{q1} = i_L - i_{p1}$, $I_{q1} = \text{RMS}(i_{q1}) = \sqrt{I_L^2 - I_{p1}^2}$. (4) i_{p1} and i_{q1} are orthogonal in the switching period T . $\int_0^T i_{p1} i_{q1} dt = 0$, $\int_0^T i_{p1} (i_L - i_{p1}) dt = P(1 - D_1)U_1/2T$, $\int_0^T u_{AB} i_L dt = I_{p1} U_{AB} T = P(1 - D_1)U_1/2$, $\int_0^T u_{AB} i_{q1} dt = -I_{q1} U_{AB} T = -P(1 - D_1)U_1/2$. (5) Similar analysis can be done to obtain the active current and the reactive current of the secondary bridge with variables referred to the primary

side $i_{p2} = P_n U_{CD} u_{CD}$, $i_{p2} = \text{RMS}(i_{p2}) = P_n U_{CD} (6) i_{q2} = i_L - i_{p2}$, $i_{q2} = \text{RMS}(i_{q2}) = \sqrt{I_{2L}^2 - I_{p2}^2}$. (7) C. Definition of Reactive Power and Power Factor Since i_{p1} and i_{q1} are orthogonal, the reactive power, the apparent power, and the power factor of primary bridge are $Q_1 = U_{AB} \cdot i_{q1}$ (8) $S_1 = \sqrt{P_1^2 + Q_1^2} = U_{AB} \cdot \sqrt{I_{p1}^2 + I_{q1}^2} = U_{AB} \cdot I_L$ (9) $\lambda_1 = P_1 / S_1 = P_1 / (U_{AB} \cdot I_L)$ (10) Note that (8)–(10) are the same as the summations of infinite series from frequency domain analysis in [9]–[11] and accord with the definitions for non sinusoidal single-phase systems [12]. However, the physical meaning and expressions are much more straightforward with the concept of reactive current through time domain analysis. Similar analysis can be done to obtain the power factor of the secondary bridge as $\lambda_2 = P_2 / S_2 = P_n U_{CD} \cdot I_L$ (11) Since the primary bridge and the secondary bridge are equally important in the power transfer, the global power factor is defined to quantify the effectiveness of modulation strategies $\lambda_{12} = \lambda_1 \lambda_2 = P_2 n U_{AB} U_{CD} I_{2L} = P_2 n U_1 U_2 I_{2L} \cdot (1 - D_1)(1 - D_2)$. (12) Authorized licensed use limited to: Tsinghua University. Downloaded on October 28, 2020 at 01:58:30 UTC from IEE Explore. Restrictions apply.



Experiment Results A prototype was built to verify the theoretical analysis. The equivalent inductance was 27.4 μH , the turns ratio of HFT was 1:1, and F_s was 40 kHz. The input dc voltage varied between 60–90 V, and the reference output voltage was set to 75 V. For the digital implementation of OGPf modulation, D_1 and D_2 with different D_0 and M was pre-calculated and stored in a lookup table. The input dc voltage and the output dc voltage were sampled, and a PI regulator took the output error to obtain D_0 . Then linear intermodulation was used to derive D_1 and D_2 from the lookup table with output D_0 and instant M . Figs. 6 and 7 show the experimental waveforms of OGPf modulation. The inner phase shift of the high voltage bridge was larger to improve the power factor. Fig. 8 shows the measured efficiency of different modulation strategies. PDF modulation provided the highest efficiency.

2. CONCLUSION

with time-domain analysis, reactive current can be divided into freewheeling reactive current and fluent reactive current. With that, reactive power and power factor are defined in the time domain with found physical meaning, and their specific expressions are derived with a concise form. An optimal global power factor modulation strategy is proposed, which can provide the highest global power factor and cover the whole power range. This method can also be adopted for other isolated DC-DC converters to achieve high power factor power transfer

Acknowledgments

The normalized IL and Pf for different voltage patterns are derived, WHERE ERMD is the remainder term and is different for each voltage pattern.

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