



## Analysis of Recent Trends in Solving *NP* Problems with New Research Directions Using Evolutionary Methods

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### ABSTRACT

Nowadays, there are different *NP* problems that are being applied to various applications. These problems are not solved in polynomial time. A wide variety of soft computing and approximation strategies are applied in solving *NP* problems to find near-optimal solutions. The recent trends in solving some of the classical *NP* problems are analyzed in this paper. The design of effective algorithms which produces a better solution with minimal computational time and space complexity is required in solving these complex real-world problems. The recent approximation and soft computing strategies applied in solving these *NP* problems are analyzed with future research directions.

Keywords : *NP*, maximum clique, *N*-queen, vertex cover, traveling salesman, 0-1 knapsack, graph coloring, genetic algorithm

### INTRODUCTION

The solutions for a lot of real-world problems are not obtained in polynomial time. An algorithm executes in a polynomial time if its complexity is in  $\Theta(n^k)$  for an input size  $n$  with  $k > 0$ , an integer. The non-deterministic polynomial (*NP*) class problems are solved on a non-deterministic Turing machine in  $\Theta(n^k)$  complexity [1]. The class *P* solves the problems in a polynomial complexity using deterministic Turing machine. The theoretical foundations of *NP*-completeness are presented in [2]. *NP* problem is converted into the satisfiability problem in  $\Theta(n^k)$  complexity. A problem *R* is in *NP-complete* if *R* is in *NP*, and some other problem from *NP* is transferred into *R* in  $\Theta(n^k)$  complexity. *NP-hardness* represents a characteristic "at least as hard as the hardest problems in *NP*".

Section 2 focuses on some of the classical *NP* problems and applications. Section 3 focuses on the analysis of recent methods applied in solving some of the *NP* problems. The critiques in some of the recent well known evolutionary methods in solving *NP* problems are analyzed in section 4 with some of the new research directions. Conclusions are highlighted in section 5.

### *NP* PROBLEMS

Let  $G = (V, E)$  be the undirected graph with  $n$  vertices, where  $V(G)$  &  $E(G)$  represents the vertex & edge sets respectively.

#### 2.1 Maximum Clique

Clique in  $G$  is defined as a complete subgraph of  $G$ . Then maximum clique finds the maximum complete subgraph of  $G$ . This *NP-hard* instance is applied in register allocation and job scheduling applications.

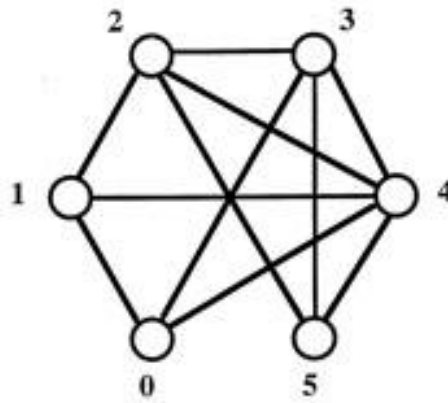


Fig 1:  $G_1$

The maximal clique is the largest subset of  $V(G)$  in which every  $v$  in  $V(G)$  is incident to every other vertex in the subset. The count of total cliques becomes double when a new vertex is added every time. Thus the problem becomes exponential growth. For the given graph shown in figure 1, the vertex set covered in the maximum clique is  $\{2, 3, 4, 5\}$  and hence the maximum clique size is 4.

**2.2 N-Queen Problem**

This NP-complete problem assigns  $N$  queens on an  $N \times N$  chessboard in which two queens should not be assigned on the same diagonal, row or column is the  $N$ -Queen problem [3]. One solution for  $N = 8$  is shown in figure 2.

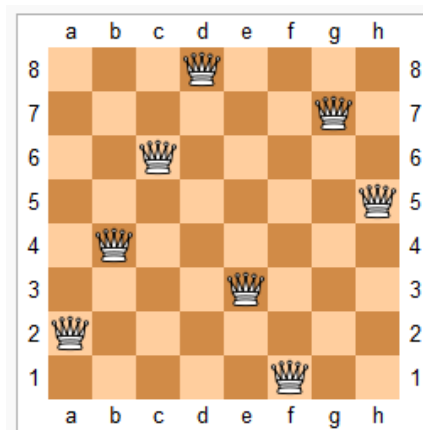


Fig 2: One solution to 8-Queens problem

**2.3 Vertex Cover Problem**

For  $G$ , the vertex cover finds a vertex set  $S \subseteq V(G)$  in which each edge  $e \in E(G)$  in  $G$  has at least one end vertex in  $S$  [4]. The partial vertex cover problem covers at least  $k$  edges of  $E(G)$  with a subset  $S'$  in  $V(G)$ . The minimum partial vertex cover determines a minimum cardinality subset of vertices  $S' \subseteq V(G)$  in which at least  $k$  edges in  $G$  cover the vertices in  $S' \subseteq V(G)$ . This problem is applied in different optimization and design problems.

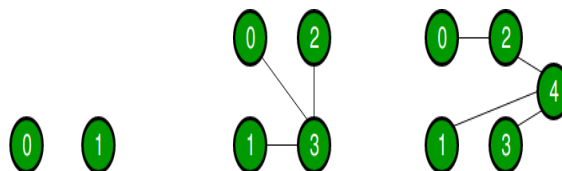


Fig 3: Graphs -  $G_1, G_2, G_3$

For the graphs shown in figure 3, the minimum vertex cover is given by  $G_1 = \{\emptyset\}$ ,  $G_2 = \{3\}$ , and  $G_3 = \{2, 4\}$  or  $\{0, 4\}$ .

**2.4 Traveling Salesman Problem (TSP)**

TSP finds the shortest distance for a traveling salesman to traverse  $n$  cities, and it returns again to the same starting city. The total cost of the tour should be minimized.

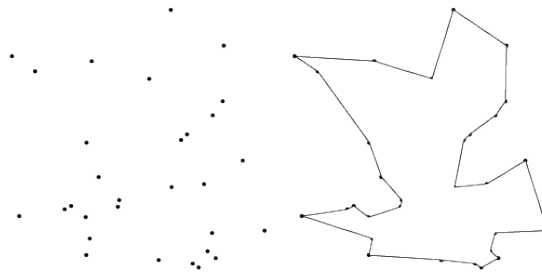


Fig 4: TSP – Graph  $G_4$  with solution

Figure 4 shows the solution for the graph  $G_4$  of the TSP.

$$\begin{pmatrix} \infty & 20 & 17 & 16 \\ 18 & \infty & 25 & 12 \\ 15 & 10 & \infty & 22 \\ 11 & 26 & 19 & \infty \end{pmatrix}$$

Consider the above edge length matrix for four cities directed graph. The optimal tour length is 50 and the optimal tour is given by City (vertex) 1  $\Rightarrow$  City (vertex) 3: City (vertex) 3  $\Rightarrow$  City (vertex) 2: City (vertex) 2  $\Rightarrow$  City (vertex) 4: City (vertex) 4  $\Rightarrow$  City (vertex) 1.

**2.5 0-1 Knapsack Problem**

Knapsack problem, *NP*-complete combinatorial optimization, is applied in material cutting, prediction of demands, cargo loading [6]. This problem maximizes the value of objects under the constraints of backpack capacity. In this decision problem, the knapsack capacity is fixed. Every object is unique and has profit and weight attributes. Given there are  $n$  unique objects with weight  $w_i$  and profit  $p_i$ , the total weight of all objects loaded with the knapsack cannot exceed its total capacity  $c$ .

If  $j^{\text{th}}$  object is placed into the knapsack then  $x_j=1$  and the profit earned is  $p_j$ . If  $j^{\text{th}}$  object is not placed into the knapsack then  $x_j=0$  and the profit earned is 0. The optimization problem is to fill a knapsack that maximizes the total profit such that  $x_j=0$  or 1,  $x_j$  and  $w_j$  are  $\geq 0$  for  $j=1, 2, \dots, n$ .

For example, the optimal solution to the knapsack instance for  $n=3$  with  $(p_1, p_2, p_3) = (12, 13, 15)$ ,  $(w_1, w_2, w_3) = (7, 5, 12)$  and  $c= 12$  is given by  $x_1=1, x_2=1, x_3=0$ . The maximum profit is 25.

**2.6 Graph Coloring Problem**

For the simple graph  $G$ , the adjacency matrix of  $G$  is  $A(G)$ , an  $n \times n$  symmetric matrix with  $A(k,j) = 1$  ( $1 \leq k, j \leq n$ ) if  $(v_j, v_k) \in E(G)$ ; and  $A(j, k) = 0$  ( $1 \leq k, j \leq n$ ) if  $(v_j, v_k)$  is not in  $E(G)$ .

$\chi(G)$  is the minimal color integer of  $G$  that defines the least number of integers needed for  $V(G)$  in such a way that no two adjoining vertices  $v_j$  and  $v_k$  are assigned the same integer [7-18]. It is used in different engineering applications such as channel assignment, allocation of registers, resource utilization, and scheduling. The color assignments of graph  $G_5$  are highlighted and are shown in figure 5.  $\chi(G_5) = 4$ .

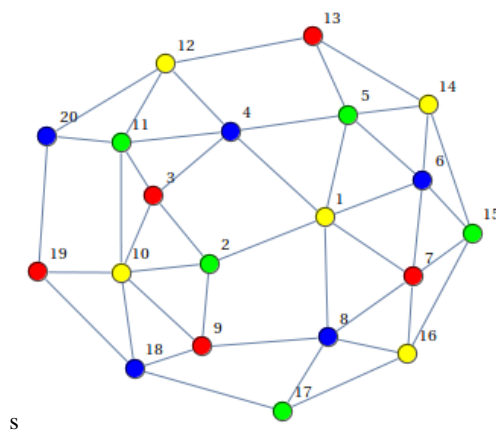


Fig 5: Graph  $G_5$  with color assignments

### 3 ANALYSIS OF NP PROBLEMS

This section focuses on the analysis of recent methods applied in solving some of the *NP* problems.

#### 3.1 Maximum Clique Problem

The artificial intelligence and meta-heuristic algorithms are applied to find the solution of maximum clique [1]. The computational time needed to determine the maximum clique depends on the size of a clique. The methods are tested on randomly generated graphs to find an incomplete solution. The branch and bound with a pruning strategy is applied to some DIMACS benchmark and random graphs [20]. The vertex order affects output performance measurements. The challenging clique benchmarks to be solved are shown in [19]. The performance of these methods should be improved further to reduce the complexity in the online training process so that a better near-optimal solution can be achieved. The heuristic with different membrane operators is developed in solving clique problem [24]. The experimentation for more large data sets in finding the maximum cliques are further expected.

#### 3.2 N-Queen Problem

There are several variations in *N*-Queen such as excluded diagonals and the blocked *N*-Queen problems that are shown as *NP*-complete [3]. The generators are presented for hard random instances to find the solution. It is expected to determine a straightforward generator for random instances of hard categories so that the computations of reductions can be eliminated. Constraint programming with propagation and backtracking searches is applied in solving the *N*-Queens problem [21]. *N*-Queens computation is both *#P*-Complete and *NP*-Complete. Counting the number of solutions using the approximation methods is computationally expensive for  $n \geq 20$ . *N*-queen problem has fewer solutions for  $n = 6$  than  $n = 5$ . The asymptotic behavior of solving the *N*-Queen problem is not yet analyzed and currently no known expression is obtained to count the exact solutions. The count of possible exact solutions for  $n = 27$  exceeds  $2.34 \times 10^{17}$ .

#### 3.3 Vertex Cover Problem

The memetic algorithm, a population-based meta-heuristic evolutionary framework embedded with local search methods, exploration and exploitation of an evolutionary process is applied in solving the minimum partial vertex cover problem [4]. The powerful backbone recombination and adaptive mutation are applied to skip the local optimum. An approximation with the shortest path calculation is designed to solve the GCP [22]. The new approximation method still is expected for solving weighted graphs. The quality of solutions for the different benchmark instances can further be improved using evolutionary algorithms so that it can be processed in real-world applications.

#### 3.4 Traveling Salesman Problem

The Physarum-inspired computational model with hill climbing strategies is applied in solving multi-objective TSP. Exact techniques such as linear programming, branch and bound, heuristic, branch and cut, and approximation methods are applied in solving TSP [30]. Even evolutionary algorithms are applied in solving optimization problems, but it suffers insufficient population diversity, premature convergence, and non-uniform distribution of solutions. The efficiency of the model can be further improved by reducing the complexity of the most critical computational operations. New insights should be gained and developed using the evolutionary model in balancing the heterogeneous features of multilayer networks to fine-tune the solution quality in community detection [5].

Clustering method is applied to maximize the performance of the evolutionary method in solving symmetric TSP [29]. This method applied clustering so that the cities are partitioned into minimal number of partitions and then every individual cluster is solved using GA. It computes the shortest Hamiltonian tour to visit every city and it consecutively visits the cities of each cluster. Minimum path lengths are applied using GA with cycle crossover and mutation such as reverse sequence, swap and slide. Cluster size, the number of clusters is not determined. New chromosome from the cluster paths are selected without any heuristics and applied for smaller problem instances. Population size *N* is set in between 160 and 240 which may increase computation cost for symmetric problem instances.

#### 3.5 0-1 Knapsack Problem

The accurate and approximate algorithms based on dynamic programming, genetic algorithm, ant colony optimization, differential evolution, membrane computing is designed in solving knapsack instances [6]. The solutions obtained by the approximation algorithms cannot completely solve some practical applications. The ant colony system with pheromone matrix optimization is developed to solve TSP and 0-1 knapsack problems [26].

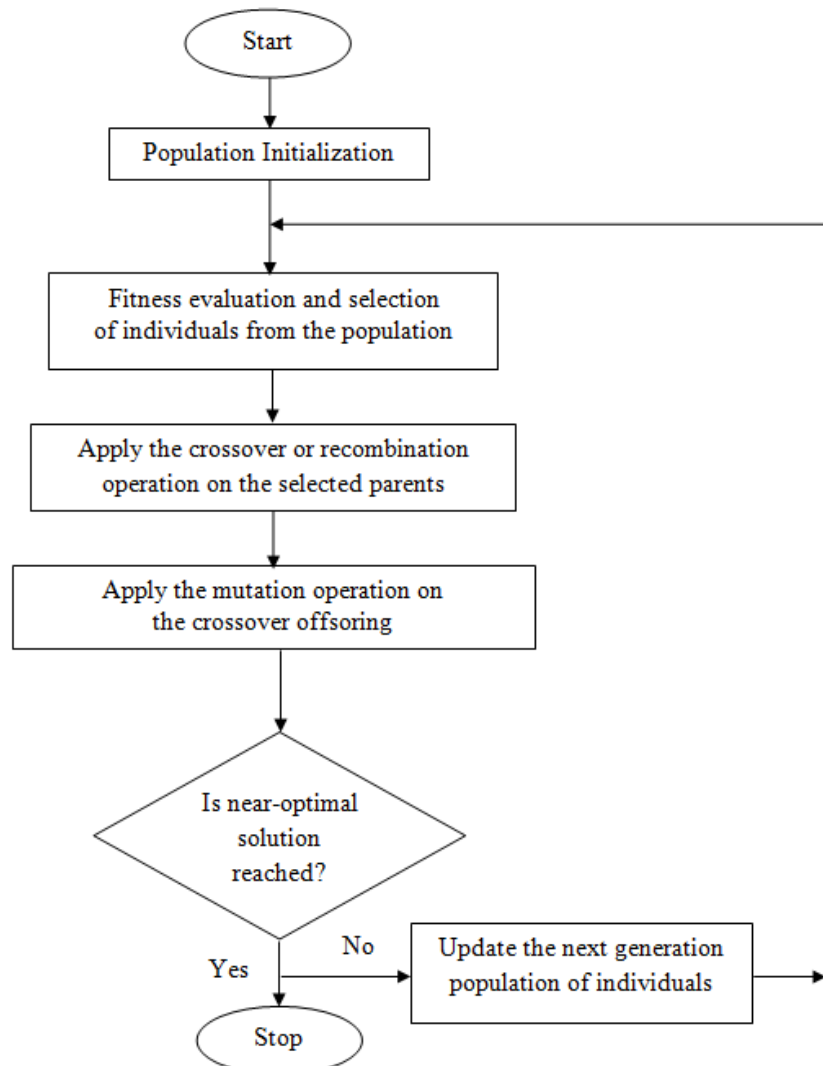
#### 3.6 Graph Coloring Problem

There are different approximations and evolutionary approaches applied to solve GCP [8-18]. These approaches reduce the minimum color used for some of the benchmark instances. For some of the benchmark instances, the minimal color has not yet obtained using the approximation and soft computing strategies. The challenging graph coloring instances are shown in [23]. The memetic method to solve GCP is developed to solve large benchmarks [25]. Furthermore, it is necessary to explore problem-based additional features so that effective operators and search strategies will be designed for large scale benchmark instances. Since GCP occupies the vast solution space, it is still necessary to design effective approximation and evolutionary methods to find the solution for large benchmark and random instances.

#### 4 CRITIQUES IN THE EVOLUTIONARY METHODS AND NEW RESEARCH DIRECTIONS

The critiques in some of the recent well known evolutionary methods in solving *NP* problems are analyzed in this section. New research directions in solving *NP* problems using the evolutionary methods are also focused.

The flow diagram of the general evolutionary technique to solve *NP* problems is depicted in figure 6. Several mutations are defined in solving some of the *NP*-hard problems and this research require further to obtain new mutations by combining existing operators in solving other *NP* problems [27].



**Fig 6: Flowchart of the general evolutionary method to solve *NP* problems**

Some of the existing methods require a large population size which increases the complexity of the evolutionary model. These methods require more exploration of search space and hence require more space requirements. Some of the operators result in premature convergence over a smaller number of generations. These operators result in a near-optimal solution which is significant from better near-optimal solutions [28]. Some of the evolutionary algorithms require a large number of runs, mutations, generations, and crossovers that are increasing the computational complexities of real-world problems. It has also been noticed that some methods produce a lower proportion of successful runs of the evolutionary algorithm [7, 31].

To overcome the limitations of these existing methods, the following new research directions are focused on solving these classical *NP* problems using evolutionary methods:

1. Evolutionary methods should maintain sufficient population diversity over the generations.

2. New strategies should be devised to keep away from the premature convergence of the optimization problem.
3. During the progress of an evolutionary algorithm, good individuals in the population are to be maintained.
4. New operators and search strategies should be designed and to be chosen rightly to obtain multiple solutions.
5. During the generations of the algorithm, the distribution of the solutions should be enhanced.
6. The imbalance between quick convergence and diversity preservation should be analyzed mathematically.
7. A new nature-inspired evolutionary model is expected to reduce the exploration space of the optimization problem.
8. The elitism strategies and selection of individuals should be chosen based on the parameters of the optimization problem.
9. For multi-objective problems, different problem parameters should be considered in evaluating the general algorithm performance.
10. The average generations, crossovers, and mutations are expected to smaller to decrease the computational complexity of the optimization.
11. The number of successful runs is expected to a high number.
12. The usage of additional memory resources should be minimized.
13. Setting a smaller size of population is expected to achieve a sufficient convergence rate.
14. Quick stochastic convergence is expected.
15. New advanced strategies are expected to embed with evolutionary operators in obtaining better near-optimal solutions.

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## 5 CONCLUSIONS

Some of the classical *NP* problems and applications are discussed in this research. The recent methods applied in solving some of the classical *NP* problems are analyzed. Some of the existing methods require a large population size which increases the complexity of the evolutionary algorithm. These methods require more exploration of search space and hence require more space complexity. Some of the operators result in premature convergence over a smaller number of generations. These operators result in a near-optimal solution which is significant from better near-optimal solutions. Some of the evolutionary algorithms require a large number of runs, mutations, generations, and crossovers that are further increasing the computational complexities of real-world problems. It has also been noticed that some methods produce a lower proportion of successful runs of the evolutionary algorithm. To overcome these critiques in these existing methods, the new research directions are focused on solving these classical *NP* problems using evolutionary methods.

### Conflict of Interests:

The authors of this paper declare that there is no conflict of interests regarding the publication of this paper.

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