



On Para-Kenmotsu Manifolds

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ABSTRACT

The object of the present paper is to study the condition of semi-symmetric type on para-Kenmotsu manifold. To show that a semi-symmetric para-Kenmotsu manifold is an η -Einstein manifold satisfies the condition $\tilde{S} \cdot \tilde{R} = 0$ and on para-Kenmotsu manifold satisfies curvature properties $\tilde{R} \cdot \tilde{R} = 0$ and $\tilde{R} \cdot \tilde{S} = 0$ is an Einstein manifold.

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1 Introduction

The notion of an almost para-contact manifold was introduced by I. Sato [7]. Since the publication of [10], paracontact metric manifolds have been studied by many authors in recent years. In this paper, consider the para-Kenmotsu manifolds. Note that the para-Kenmotsu structure was introduced by J. We lyczko in [13] for 3-dimensional normal almost paracontact metric structures. A similar notion called P-Kenmotsu structure appears in the paper of B. B. Sinha and K. L. Sai Prasad [12]. The importance of para-Kenmotsu geometry has been pointed out especially in the last years by several papers highlighting the exchanges with the theory of para-Kähler manifolds and its role in semi-Riemannian geometry and mathematical physics [3, 4, 5, 8, 9].

The present paper is organized as follows: After preliminaries on para-Kenmotsu manifold in section 2. We study in section 3, the semi-symmetric type condition on para-Kenmotsu manifold is an η -Einstein manifold. In section 4, a Ricci semi-symmetric condition on para-Kenmotsu manifold is an η -Einstein manifold. Further, In the section 5, Semi-symmetric type condition on para-Kenmotsu manifold is an η -Einstein manifold

2 Preliminaries

An n -dimensional differentiable manifold M^n is said to have almost para-contact structure (ϕ, ξ, η) , where ϕ is a tensor field of type $(1,1)$, ξ is a vector field known as characteristic vector field and η is a 1-form satisfying the following relations

$$\phi^2(X) = X - \eta(X)\xi, \quad (2.1)$$

$$\eta(\phi X) = 0, \quad (2.2)$$

and

$$\phi(\xi) = 0, \quad (2.3)$$

$$\eta(\xi) = 1. \quad (2.4)$$

A differentiable manifold with almost para-contact structure (ϕ, ξ, η) is called an almost para-contact manifold. Further, if the manifold M^n has a semi-Riemannian metric g satisfying

$$\eta(X) = g(X, \xi) \quad (2.5)$$

and

$$g(\phi X, \phi Y) = -g(X, Y) + \eta(X)\eta(Y). \quad (2.6)$$

Then the structure (ϕ, ξ, η, g) satisfying conditions (2.1) to (2.6) is called an almost para-contact Riemannian structure and the manifold M^n with such a structure is called an almost para-contact Riemannian manifold [1, 7].

Now we briefly present an account of an analogue of the Kenmotsu manifold in para-contact geometry which will be called para-Kenmotsu.

Definition 2.1 *The almost paracontact metric structure (ϕ, ξ, η, g) is para-Kenmotsu should this relation hold [2, 11], if the Levi-Civita connection ∇ of g satisfies $(\nabla_X \phi)Y = g(\phi X, Y)\xi - \eta(Y)\phi X$, for any $X, Y \in \mathfrak{X}(M)$.*

On a para-Kenmotsu manifold [2, 8], by the following relations hold:

$$(\nabla_X \phi)Y = g(\phi X, Y)\xi - \eta(Y)\phi X, \quad (2.7)$$

$$\nabla_X \xi = X - \eta(X)\xi, \quad (2.8)$$

$$(\nabla_X \eta)Y = g(X, Y) - \eta(X)\eta(Y), \quad (2.9)$$

$$\eta(R(X, Y, Z)) = g(X, Z)\eta(Y) - g(Y, Z)\eta(X), \quad (2.10)$$

$$R(X, Y, \xi) = \eta(X)Y - \eta(Y)X, \quad (2.11)$$

$$R(X, \xi, Y) = -R(\xi, X, Y) = g(X, Y)\xi - \eta(Y)X, \quad (2.12)$$

$$S(\phi X, \phi Y) = -(n-1)g(\phi X, \phi Y), \quad (2.13)$$

$$S(X, \xi) = -(n-1)\eta(X), \quad (2.14)$$

$$Q\xi = -(n-1)\xi, \quad (2.15)$$

$$r = -n(n-1), \quad (2.16)$$

for any vector fields X, Y, Z , where Q is the Ricci operator that is $g(QX, Y) = S(X, Y)$, S is the Ricci tensor and r is the scalar curvature.

In A. M. Blaga [2], has given an example on the para-Kenmotsu manifold.

Example 2.1 [2] We consider the three dimensional manifold $M^3 = \{(x, y, z) \in \mathbb{R}^3, z \neq 0\}$, where (x, y, z) are the standard co-ordinates in \mathbb{R}^3 . The vector fields

$$e_1 := \frac{\partial}{\partial x}, \quad e_2 := \frac{\partial}{\partial y}, \quad e_3 := -\frac{\partial}{\partial z}$$

are linearly independent at each point of the manifold.

Define

$$\phi := \frac{\partial}{\partial y} \otimes dx + \frac{\partial}{\partial x} \otimes dy, \quad \xi := -\frac{\partial}{\partial z}, \quad \eta := -dz,$$

$$g := dx \otimes dx - dy \otimes dy + dz \otimes dz.$$

Then it follows that

$$\phi e_1 = e_2, \quad \phi e_2 = e_1, \quad \phi e_3 = 0,$$

$$\eta(e_1) = 0, \quad \eta(e_2) = 0, \quad \eta(e_3) = 1.$$

Let ∇ be the Levi-Civita connection with respect to metric g . Then, we have

$$[e_1, e_2] = 0, \quad [e_2, e_3] = 0, \quad [e_3, e_1] = 0.$$

The Riemannian connection ∇ of the metric g is deduced from Koszul's formula

$$2g(\nabla_X Y, Z) = X(g(Y, Z)) + Y(g(Z, X)) - Z(g(X, Y)) \\ - g(X, [Y, Z]) + g(Y, [Z, X]) + g(Z, [X, Y]).$$

Then Koszul's formula yields

$$\nabla_{e_1} e_1 = -e_3, \quad \nabla_{e_1} e_2 = 0, \quad \nabla_{e_1} e_3 = e_1,$$

$$\nabla_{e_2} e_1 = 0, \quad \nabla_{e_2} e_2 = e_3, \quad \nabla_{e_2} e_3 = e_2,$$

$$\nabla_{e_3} e_1 = e_1, \quad \nabla_{e_3} e_2 = e_2, \quad \nabla_{e_3} e_3 = 0.$$

These results show that the manifold satisfies

$$\nabla_X \xi = X - \eta(X)\xi,$$

for $\xi = e_3$. Hence, the manifold under consideration is para-Kenmotsu manifold of dimension three.

A para-Kenmotsu manifold is said to be an η -Einstein manifold if its Ricci tensor S is of the form

$$S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y) \tag{2.17}$$

for the vector fields X, Y , where a and b are functions on M^n .

3 Semi-Symmetric on Para-Kenmotsu Manifold

Definition 3.1 A para-Kenmotsu manifold is said to be semi-symmetric [9] if the condition

$$R(X, Y) \cdot R = 0, \tag{3.1}$$

holds for all vector fields X, Y .

Theorem 3.1 *A semi-symmetric condition on para-Kenmotsu manifold is an Einstein manifold.*

Proof: Consider

$$(R(X, Y) \cdot R)(Z, W, U) = 0 \quad (3.2)$$

for all vector fields X, Y, Z, W and U . Then, in particular for $X = \xi$, we have

$$(R(\xi, X) \cdot R)(Y, Z, W) = 0,$$

which, implies that

$$0 = R(\xi, X, R(Y, Z, W)) - R(R(\xi, X, Y), Z, W) \\ - R(Y, R(\xi, X, Z), W) - R(Y, Z, R(\xi, X, W)).$$

Now, using (2.10), (2.12) in the above equation, we find that

$$'R(Y, Z, W, X)\xi = [g(Y, W)\eta(Z) - g(Z, W)\eta(Y)]X \\ - \eta(Y)R(X, Z, W) + g(X, Y)R(\xi, Z, W) - \eta(Z)R(Y, X, W) \\ + g(X, Z)R(Y, \xi, W) - \eta(W)R(Y, Z, X) + g(X, W)R(Y, Z, \xi).$$

Again, using the equations (2.10), (2.11) and (2.12), in the above equation and taking inner product with ξ , we get

$$'R(Y, Z, W, X) = g(X, Z)g(Y, W) - g(X, Y)g(Z, W).$$

Now, contracting the above equation with respect to X and Y , we obtain

$$S(W, Z) = (1 - n)g(W, Z).$$

This proves the theorem.

4 Ricci Semi-Symmetric on Para-Kenmotsu Manifold

Definition 4.1 *A para-Kenmotsu manifold is said to be Ricci semi-symmetric [6] if the condition*

$$R(X, Y) \cdot S = 0, \quad (4.1)$$

holds for all vector fields X, Y .

Theorem 4.1 *A Ricci semi-symmetric condition on para-Kenmotsu manifold is an Einstein manifold.*

Proof: Consider

$$(R(X, Y) \cdot S)(Z, W) = 0,$$

which gives

$$S(R(\xi, Y, Z), W) + S(Z, R(\xi, Y, W)) = 0.$$

Using equations (2.12), (2.14) in above equation, we get

$$S(Y, W)\eta(Z) + (n - 1)g(Y, Z)\eta(W) \\ + S(Y, Z)\eta(W) + (n - 1)g(Y, W)\eta(Z) = 0.$$

Putting $Z = \xi$ in the above equation and using (2.4), (2.5) and (2.14), we get

$$S(Y, W) = -(n - 1)g(Y, W)$$

This proves the theorem.

5 Semi-Symmetric Type on Para-Kenmotsu Manifold

Definition 5.1 A para-Kenmotsu manifold is said to be semi-symmetric type if the condition

$$S(X, Y) \cdot R = 0, \quad (5.1)$$

holds for all vector fields X, Y .

Theorem 5.1 A semi-symmetric type condition on para-Kenmotsu manifold is an η -Einstein manifold.

Proof: Consider

$$S(\xi, X) \cdot R = 0,$$

which gives

$$\begin{aligned} & S(X, R(Y, Z, W))\xi - S(\xi, R(Y, Z, W))X + S(Y, X)R(\xi, Z, W) \\ & - S(Y, \xi)R(X, Z, W) + S(X, Z)R(Y, \xi, W) - S(Z, \xi)R(Y, X, W) \\ & + S(W, X)R(Y, Z, \xi) - S(W, \xi)R(Y, Z, X) = 0. \end{aligned}$$

Taking inner product with ξ and using equations (2.5), (2.10), (2.12), (2.14) in above equation, we get

$$\begin{aligned} & S(X, R(Y, Z, W)) + 2(n-1)\eta(X)\eta(Z)g(Y, W) - 2(n-1)\eta(X)\eta(Y)g(Z, W) \\ & + \eta(W)\eta(Z)S(Y, X) - S(Y, X)g(Z, W) + S(Z, X)g(Y, W) - \eta(W)\eta(Y)S(Z, X) \\ & + (n-1)\eta(W)\eta(Z)g(Y, X) - (n-1)\eta(W)\eta(Y)g(Z, X) = 0. \end{aligned}$$

Putting $W = \xi$ in the above equation and using (2.11), we get

$$\eta(Y)S(Z, X) - \eta(Z)S(Y, X) + (n-1)\eta(Z)g(Y, X) - (n-1)\eta(Y)g(Z, X) = 0.$$

Again putting $Z = \xi$ in the above equation and using (2.4), (2.5), (2.14), we get

$$S(Y, X) = (n-1)g(Y, X) - 2(n-1)\eta(X)\eta(Y).$$

This proves the theorem.

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